

#### MLFB-Ordering data

6SL3210-1KE21-7AP1



Item no. :
Consignment no. :

Project:

Client order no. :
Order no. :
Offer no. :
Remarks :

# Rated data Input **Number of phases** 3 AC Line voltage 380 ... 480 V +10 % -20 % Line frequency 47 ... 63 Hz Rated current (LO) 21.50 A Rated current (HO) 18.20 A Output **Number of phases** 3 АС Rated voltage 400 V Rated power IEC 400V (LO) 7.50 kW Rated power NEC 480V (LO) 10.00 hp Rated power IEC 400V (HO) 5.50 kW Rated power NEC 480V (HO) 7.50 hp Rated current (IN) 17.00 A Rated current (LO) 16.50 A Rated current (HO) 12.50 A Max. output current 25.00 A 4 kHz Pulse frequency Output frequency for vector control 0 ... 240 Hz Output frequency for V/f control 0 ... 550 Hz

Overioad Capability	Overload o	apability	
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### Low Overload (LO)

 $150\,\%$  base load current IL for 3 s, followed by  $110\,\%$  base load current IL for  $57\,s$  in a  $300\,s$  cycle time

#### High Overload (HO)

 $200\ \%$  base load current IH for 3 s, followed by 150 % base load current IH for 57 s in a 300 s cycle time

General tech. specifications		
	0.70 0.05	
Power factor λ	0.70 0.85	
Offset factor cos φ	0.95	
Efficiency η	0.97	
Sound pressure level (1m)	63 dB	
Power loss	0.24 kW	
Filter class (integrated)	Class A	

Ambient conditions			
Cooling	Air cooling using an integrated fan		
Cooling air requirement	0.009 m³/s (0.318 ft³/s)		
Installation altitude 1000 m (3280.84 ft)			
Ambient temperature			
Operation	-10 40 °C (14 104 °F)		
Transport	-40 70 °C (-40 158 °F)		
Storage	-40 70 °C (-40 158 °F)		
Relative humidity			

# 95 % At 40 °C (104 °F), condensation and icing not permissible

Closed-loop control techniques		
V/f linear / square-law / parameterizable	Yes	
V/f with flux current control (FCC)	Yes	
V/f ECO linear / square-law	Yes	
Sensorless vector control	Yes	
Vector control, with sensor	No	
Encoderless torque control	No	
Torque control, with encoder	No	



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			Figure simi
Mechanical data		Com	nmunication
Degree of protection	IP20 / UL open type	Communication	PROFIBUS DP
Size	FSB	Connections	
Net weight	2.30 kg (5.07 lb)	Signal cable	
Width	100 mm (3.94 in)	Conductor cross-section	0.15 1.50 mm² (AWG 24 AWG 16)
Height	196 mm (7.72 in)	Line side	
Depth	203 mm (7.99 in)	Version	Plug-in screw terminals
Inputs / ou	tputs	Conductor cross-section	4.00 6.00 mm² (AWG 12 AWG 10)
Standard digital inputs		Motor end	
Number	6	Version	Plug-in screw terminals
Switching level: 0→1	11 V	Conductor cross-section	4.00 6.00 mm² (AWG 12 AWG 10)
Switching level: 1→0	5 V	DC link (for braking resistor)	)
Max. inrush current	15 mA	Version	Plug-in screw terminals
Fail-safe digital inputs		Conductor cross-section	4.00 6.00 mm² (AWG 12 AWG 10)
Number	1	Line length, max.	15 m (49.21 ft)
Digital outputs		PE connection	On housing with M4 screw
Number as relay changeover contact	1	Max. motor cable length	on nousing with wire screw
Output (resistive load)	DC 30 V, 0.5 A	Shielded	50 m (164.04 ft)
Number as transistor	1	Unshielded	150 m (492.13 ft)
Output (resistive load)	DC 30 V, 0.5 A	Standards	
Analog / digital inputs		Compliance with standards	UL, cUL, CE, C-Tick (RCM)
Number	1 (Differential input)		
Resolution	10 bit	CE marking	EMC Directive 2004/108/EC, Low-Voltag Directive 2006/95/EC
Switching threshold as digital in	put		
0→1	4 V		
1→0	1.6 V		
Analog outputs			

# PTC/ KTY interface

Number

1 motor temperature sensor input, sensors that can be connected: PTC, KTY and Thermo-Click, accuracy  $\pm 5~^\circ\text{C}$ 

1 (Non-isolated output)



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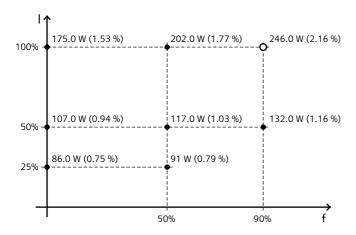
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#### Figure similar

# Converter losses to EN 50598-2\*

Efficiency class	IE2
Comparison with the reference converter (90% / 100%)	-63.01 %



The percentage values show the losses in relation to the rated apparent power of the converter.

The diagram shows the losses for the points (as per standard EN 50598) of the relative torque generating current (I) over the relative motor stator frequency(f). The values are valid for the basic version of the converter without options/components.

\*converted values