

MLFB-Ordering data

6SL3210-1KE21-3UP1



Figure similar

Client order no.: Order no. : Offer no. : Remarks:

Item no.: Consignment no. : Project:

Rated d	ata
nput	
Number of phases	3 AC
Line voltage	380 480 V +10 % -20 %
Line frequency	47 63 Hz
Rated current (LO)	16.50 A
Rated current (HO)	12.80 A
Output	
Number of phases	3 AC
Rated voltage	400 V
Rated power IEC 400V (LO)	5.50 kW
Rated power NEC 480V (LO)	7.50 hp
Rated power IEC 400V (HO)	4.00 kW
Rated power NEC 480V (HO)	5.00 hp
Rated current (IN)	13.00 A
Rated current (LO)	12.50 A
Rated current (HO)	8.80 A
Max. output current	17.60 A
Pulse frequency	4 kHz
Output frequency for vector control	0 240 Hz
Output frequency for V/f control	0 550 Hz

Overload ca	pability
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Low Overload (LO)

150 % base load current IL for 3 s, followed by 110 % base load current IL for 57 s in a 300 s cycle time

High Overload (HO)

200 % base load current IH for 3 s, followed by 150 % base load current IH for 57 s in a 300 s cycle time

General tech. specifications			
Power factor λ	0.70 0.85		
Offset factor see a	0.95		
Offset factor cos φ	0.95		
Efficiency η	0.97		
Sound pressure level (1m)	63 dB		
Power loss	0.18 kW		
Filter class (integrated)	Unfiltered		

Ambient conditions			
Cooling	Air cooling using an integrated fan		
Cooling air requirement	0.009 m³/s (0.318 ft³/s)		
Installation altitude	1000 m (3280.84 ft)		
Ambient temperature			
Operation	-10 40 °C (14 104 °F)		
Transport	-40 70 °C (-40 158 °F)		
Storage	-40 70 °C (-40 158 °F)		
Relative humidity			

95 % At 40 °C (104 °F), condensation Max. operation and icing not permissible

Closed-loop control techniques		
V/f linear / square-law / parameterizable	Yes	
V/f with flux current control (FCC)	Yes	
V/f ECO linear / square-law	Yes	
Sensorless vector control	Yes	
Vector control, with sensor	No	
Encoderless torque control	No	
Torque control, with encoder	No	



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Mechanica	data	Com	munication
Degree of protection	IP20 / UL open type	Communication	PROFIBUS DP
Size	FSB	Connections	
Net weight	2.30 kg (5.07 lb)	Signal cable	
Width	100 mm (3.94 in)	Conductor cross-section	0.15 1.50 mm² (AWG 24 AWG 16)
Height	196 mm (7.72 in)	Line side	
Depth	203 mm (7.99 in)	Version	Plug-in screw terminals
Inputs / ou	tputs	Conductor cross-section	4.00 6.00 mm² (AWG 12 AWG 10)
Standard digital inputs		Motor end	
Number	6	Version	Plug-in screw terminals
Switching level: 0→1	11 V	Conductor cross-section	4.00 6.00 mm² (AWG 12 AWG 10)
Switching level: 1→0	5 V	DC link (for braking resistor)	
Max. inrush current	15 mA	Version	Plug-in screw terminals
Fail-safe digital inputs		Conductor cross-section	4.00 6.00 mm² (AWG 12 AWG 10)
Number	1	Line length, max.	15 m (49.21 ft)
Digital outputs		PE connection	On housing with M4 screw
Number as relay changeover contact	1	Max. motor cable length	
Output (resistive load)	DC 30 V, 0.5 A	Shielded	50 m (164.04 ft)
Number as transistor	1	Unshielded	150 m (492.13 ft)
Output (resistive load)	DC 30 V, 0.5 A	Si	tandards
Analog / digital inputs		Compliance with standards	UL, cUL, CE, C-Tick (RCM)
Number	1 (Differential input)		
Resolution	10 bit	CE marking	EMC Directive 2004/108/EC, Low-Voltage Directive 2006/95/EC
Switching threshold as digital in	put		

Analog outputs

0 → 1

1→0

Number 1 (Non-isolated output)

PTC/ KTY interface

1 motor temperature sensor input, sensors that can be connected: PTC, KTY and Thermo-Click, accuracy $\pm 5~^\circ\text{C}$

4 V

1.6 V



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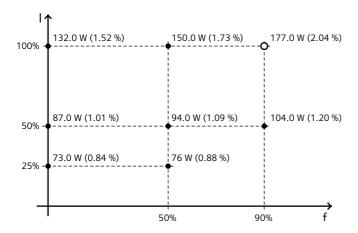
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Figure similar

Converter losses to EN 50598-2*

Efficiency class	IE2
Comparison with the reference converter (90% / 100%)	-66.06 %



The percentage values show the losses in relation to the rated apparent power of the converter.

The diagram shows the losses for the points (as per standard EN 50598) of the relative torque generating current (I) over the relative motor stator frequency(f). The values are valid for the basic version of the converter without options/components.

*converted values