

## **MLFB-Ordering data**

6SL3210-1KE21-3AB1



Client order no. :
Order no. :
Offer no. :
Remarks :

Item no. : Consignment no. : Project :

Rated data		
Input		
Number of phases	3 AC	
Line voltage	380 480 V +10 % -20 %	
Line frequency	47 63 Hz	
Rated current (LO)	16.50 A	
Rated current (HO)	12.80 A	
Output		
Number of phases	3 AC	
Rated voltage	400 V	
Rated power IEC 400V (LO)	5.50 kW	
Rated power NEC 480V (LO)	7.50 hp	
Rated power IEC 400V (HO)	4.00 kW	
Rated power NEC 480V (HO)	5.00 hp	
Rated current (IN)	13.00 A	
Rated current (LO)	12.50 A	
Rated current (HO)	8.80 A	
Max. output current	17.60 A	
Pulse frequency	4 kHz	
Output frequency for vector control	0 240 Hz	
Output frequency for V/f control	0 550 Hz	

Overload capability	l capability
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## Low Overload (LO)

 $150\ \%$  base load current IL for 3 s, followed by  $110\ \%$  base load current IL for 57 s in a  $300\ s$  cycle time

#### High Overload (HO)

 $200\,\%$  base load current IH for 3 s, followed by 150 % base load current IH for 57 s in a 300 s cycle time

General tech. specifications		
Power factor λ	0.70 0.85	
Offset factor cos φ	0.95	
Efficiency η	0.97	
Sound pressure level (1m)	63 dB	
Power loss	0.18 kW	
Filter class (integrated)	Class A	

Ambient conditions		
Cooling	Air cooling using an integrated fan	
Cooling air requirement	0.009 m <sup>3</sup> /s (0.318 ft <sup>3</sup> /s)	
Installation altitude	1000 m (3280.84 ft)	
Ambient temperature		
Operation	-10 40 °C (14 104 °F)	
Transport	-40 70 °C (-40 158 °F)	
Storage	-40 70 °C (-40 158 °F)	
Relative humidity		

Closed-loop control techniques		
V/f linear / square-law / parameterizable	Yes	
V/f with flux current control (FCC)	Yes	
V/f ECO linear / square-law	Yes	
Sensorless vector control	Yes	
Vector control, with sensor	No	
Encoderless torque control	No	
Torque control, with encoder	No	



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Size       FSE         Net weight       2.3         Width       100         Height       190         Depth       200         Inputs / output         Standard digital inputs         Number       6         Switching level: 0→1       11         Switching level: 1→0       5 V	0 / UL open type	Communication	munication  USS/MODBUS RTU
Size FSE  Net weight 2.3  Width 100  Height 190  Depth 200  Inputs / output  Standard digital inputs  Number 6  Switching level: $0 \rightarrow 1$ 11  Switching level: $1 \rightarrow 0$ 5 v			USS/MODBUS RTU
Net weight       2.3         Width       100         Height       190         Depth       200         Inputs / output         tandard digital inputs         Number       6         Switching level: 0→1       11         Switching level: 1→0       5 ∨	В		
Width100Height190Depth200Inputs / outputtandard digital inputsNumber6Switching level: $0 \rightarrow 1$ 11Switching level: $1 \rightarrow 0$ 5 V		Co	nnections
Height 199  Depth 200  Inputs / output  Standard digital inputs  Number 6  Switching level: 0→1 11  Switching level: 1→0 5 V	80 kg (5.07 lb)	Signal cable	
Inputs / output tandard digital inputs  Number 6  Switching level: 0→1 11  Switching level: 1→0 5 ∨	0 mm (3.94 in)	Conductor cross-section	0.15 1.50 mm² (AWG 24 AWG 16
Inputs / output  Standard digital inputs  Number 6  Switching level: $0 \rightarrow 1$ 11  Switching level: $1 \rightarrow 0$ 5 V	6 mm (7.72 in)	Line side	
tandard digital inputs  Number 6  Switching level: $0 \rightarrow 1$ 11  Switching level: $1 \rightarrow 0$ 5 V	3 mm (7.99 in)	Version	Plug-in screw terminals
Number 6  Switching level: $0 \rightarrow 1$ 11  Switching level: $1 \rightarrow 0$ 5 V	s	Conductor cross-section	4.00 6.00 mm² (AWG 12 AWG 1
Switching level: $0 \rightarrow 1$ 11  Switching level: $1 \rightarrow 0$ 5 V		Motor end	
Switching level: 1→0 5 V		Version	Plug-in screw terminals
-	V	Conductor cross-section	4.00 6.00 mm² (AWG 12 AWG 1
Max. inrush current 15	/	DC link (for braking resistor)	
	mA	Version	Plug-in screw terminals
ail-safe digital inputs		Conductor cross-section	4.00 6.00 mm² (AWG 12 AWG 1
Number 1		Line length, max.	15 m (49.21 ft)
igital outputs		PE connection	On housing with M4 screw
Number as relay changeover contact 1		Max. motor cable length	Off flousing with MH screw
Output (resistive load) DC	30 V, 0.5 A	Shielded	50 m (164.04 ft)
Number as transistor 1		Unshielded	150 m (492.13 ft)
Output (resistive load) DC	30 V, 0.5 A	St	tandards
nalog / digital inputs		Compliance with standards	UL, cUL, CE, C-Tick (RCM)
Number 1 (	Differential input)		
Resolution 10		CC	EMC Directive 2004/108/EC, Low-Vol
witching threshold as digital input	bit	CE marking	Directive 2006/95/EC

0 → 1	4 V
1→0	1.6 V

# **Analog outputs**

Number	1 (Non-isolated output)
	. (

# PTC/ KTY interface

1 motor temperature sensor input, sensors that can be connected: PTC, KTY and Thermo-Click, accuracy  $\pm 5~^{\circ}\text{C}$ 



#### MLFB-Ordering data

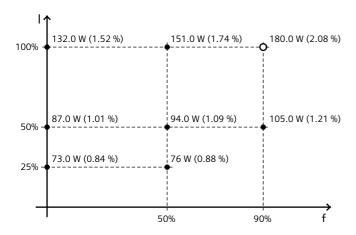
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#### Figure similar

# Converter losses to EN 50598-2\*

Efficiency class	IE2
Comparison with the reference converter (90% / 100%)	-65.39 %



The percentage values show the losses in relation to the rated apparent power of the converter.

The diagram shows the losses for the points (as per standard EN 50598) of the relative torque generating current (I) over the relative motor stator frequency(f). The values are valid for the basic version of the converter without options/components.

\*converted values