

MLFB-Ordering data

6SL3210-1KE18-8AB1



Figure similar

Client order no. : Order no. : Offer no. : Remarks:

Item no.: Consignment no. : Project:

Rated da	nta	
Input		
Number of phases	3 AC	
Line voltage	380 480 V +10 % -20 %	
Line frequency	47 63 Hz	
Rated current (LO)	11.40 A	
Rated current (HO)	10.60 A	
Output		
Number of phases	3 AC	
Rated voltage	400 V	
Rated power IEC 400V (LO)	4.00 kW	
Rated power NEC 480V (LO)	5.00 hp	
Rated power IEC 400V (HO)	3.00 kW	
Rated power NEC 480V (HO)	4.00 hp	
Rated current (IN)	9.00 A	
Rated current (LO)	8.80 A	
Rated current (HO)	7.30 A	
Max. output current	14.60 A	
Pulse frequency	4 kHz	
Output frequency for vector control	0 240 Hz	
Output frequency for V/f control	0 550 Hz	

Overload c	apability
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Low Overload (LO)

150 % base load current IL for 3 s, followed by 110 % base load current IL for 57 s in a 300 s cycle time

High Overload (HO)

200 % base load current IH for 3 s, followed by 150 % base load current IH for 57 s in a 300 s cycle time

General tech. specifications		
Power factor λ	0.70 0.85	
Offset factor cos φ	0.95	
Efficiency η	0.97	
Sound pressure level (1m)	52 dB	
Power loss	0.15 kW	
Filter class (integrated)	Class A	

Ambient conditions		
Cooling	Air cooling using an integrated fan	
Cooling air requirement	0.005 m³/s (0.177 ft³/s)	
Installation altitude	1000 m (3280.84 ft)	
Ambient temperature		
Operation	-10 40 °C (14 104 °F)	
Transport	-40 70 °C (-40 158 °F)	
Storage	-40 70 °C (-40 158 °F)	
Relative humidity		

Max. operation	95 % At 40 °C (104 °F), condensation and icing not permissible
Closed-loo	p control techniques

Closed-loop control techniques		
V/f linear / square-law / parameterizable	Yes	
V/f with flux current control (FCC)	Yes	
V/f ECO linear / square-law	Yes	
Sensorless vector control	Yes	
Vector control, with sensor	No	
Encoderless torque control	No	
Torque control, with encoder	No	



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Mechanical data		Cor	Communication	
Degree of protection	IP20 / UL open type	Communication	USS/MODBUS RTU	
Size	FSA	Connections		
Net weight	1.70 kg (3.75 lb)	Signal cable		
Width	73 mm (2.87 in)	Conductor cross-section	0.15 1.50 mm² (AWG 24 AWG 16)	
Height	196 mm (7.72 in)	Line side		
Depth	203 mm (7.99 in)	Version	Plug-in screw terminals	
Inputs / out	tputs	Conductor cross-section	1.00 2.50 mm² (AWG 18 AWG 14)	
Standard digital inputs		Motor end		
Number	6	Version	Plug-in screw terminals	
Switching level: 0→1	11 V	Conductor cross-section	1.00 2.50 mm² (AWG 18 AWG 14)	
Switching level: 1→0	5 V	DC link (for braking resisto	r)	
Max. inrush current	15 mA	Version	Plug-in screw terminals	
Fail-safe digital inputs		Conductor cross-section	1.00 2.50 mm² (AWG 18 AWG 14)	
Number	1	Line length, max.	15 m (49.21 ft)	
Digital outputs		PE connection	On housing with M4 screw	
Number as relay changeover contact	1	Max. motor cable length	Off flousing with M4 screw	
Output (resistive load)	DC 30 V, 0.5 A	Shielded	50 m (164.04 ft)	
Number as transistor	1	Unshielded	150 m (492.13 ft)	
Output (resistive load)	DC 30 V, 0.5 A	Standards		
Analog / digital inputs		Compliance with standards	UL, cUL, CE, C-Tick (RCM)	
Number	1 (Differential input)	,		
Resolution	10 bit	CE marking	EMC Directive 2004/108/EC, Low-Voltag Directive 2006/95/EC	
Switching threshold as digital in	put			
0→1	4 V			

Analog outputs

1 → 0

Number 1 (Non-isolated output)

PTC/ KTY interface

1 motor temperature sensor input, sensors that can be connected: PTC, KTY and Thermo-Click, accuracy $\pm 5~^\circ\text{C}$

1.6 V



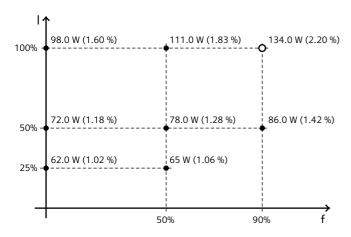
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Converter losses to EN 50598-2*

Efficiency class	IE2
Comparison with the reference converter (90% /	-65.57 %



The percentage values show the losses in relation to the rated apparent power of the converter.

The diagram shows the losses for the points (as per standard EN 50598) of the relative torque generating current (I) over the relative motor stator frequency(f). The values are valid for the basic version of the converter without options/components.

^{*}converted values