

MLFB-Ordering data

Remarks:

6SL3210-1KE17-5UB1



Client order no. :
Order no. :
Offer no. :

Item no. : Consignment no. : Project :

Rated data

kated data		
Input		
Number of phases	3 AC	
Line voltage	380 480 V +10 % -20 %	
Line frequency	47 63 Hz	
Rated current (LO) 9.50 A		
Rated current (HO)	8.20 A	
Output		
Number of phases	3 AC	
Rated voltage	400 V	
Rated power IEC 400V (LO)	3.00 kW	
Rated power NEC 480V (LO)	4.00 hp	
Rated power IEC 400V (HO)	2.20 kW	
Rated power NEC 480V (HO)	3.00 hp	
Rated current (IN)	7.50 A	
Rated current (LO)	7.30 A	
Rated current (HO)	5.60 A	
Max. output current	11.20 A	
Pulse frequency	4 kHz	
Output frequency for vector control	0 240 Hz	
Output frequency for V/f control	0 550 Hz	

Overload capability

Low Overload (LO)

 $150\ \%$ base load current IL for 3 s, followed by $110\ \%$ base load current IL for 57 s in a $300\ s$ cycle time

High Overload (HO)

 $200\ \%$ base load current IH for 3 s, followed by 150 % base load current IH for 57 s in a 300 s cycle time

General tech.	specifications
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0.70 0.85
0.95
0.97
52 dB
0.14 kW
Unfiltered

Ambient conditions

Cooling	Air cooling using an integrated fan
Cooling air requirement	0.005 m³/s (0.177 ft³/s)
Installation altitude	1000 m (3280.84 ft)

Ambient temperature

Operation	-10 40 °C (14 104 °F)
Transport	-40 70 °C (-40 158 °F)
Storage	-40 70 °C (-40 158 °F)

Relative humidity

	95 % At 40 °C (104 °F), condensation
Max. operation	and icing not permissible

Closed-loop control techniques

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V/f linear / square-law / parameterizable	Yes
V/f with flux current control (FCC)	Yes
V/f ECO linear / square-law	Yes
Sensorless vector control	Yes
Vector control, with sensor	No
Encoderless torque control	No
Torque control, with encoder	No



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Mechanical	l data	Com	Figure simunication
Degree of protection	IP20 / UL open type	Communication	USS/MODBUS RTU
Size	FSA	Connections	
Net weight	1.70 kg (3.75 lb)	Signal cable	
Width	73 mm (2.87 in)	Conductor cross-section	0.15 1.50 mm² (AWG 24 AWG 16)
Height	196 mm (7.72 in)	Line side	
Depth	203 mm (7.99 in)	Version	Plug-in screw terminals
Inputs / out	tputs	Conductor cross-section	1.00 2.50 mm² (AWG 18 AWG 14)
Standard digital inputs		Motor end	
Number	6	Version	Plug-in screw terminals
Switching level: 0→1	11 V	Conductor cross-section	1.00 2.50 mm² (AWG 18 AWG 14)
Switching level: 1→0	5 V	DC link (for braking resistor)	
Max. inrush current	15 mA	Version	Plug-in screw terminals
Fail-safe digital inputs		Conductor cross-section	1.00 2.50 mm² (AWG 18 AWG 14)
Number	1		15 m (49.21 ft)
Digital outputs		Line length, max.	
Number as relay changeover contact	1	PE connection Max. motor cable length	On housing with M4 screw
Output (resistive load)	DC 30 V, 0.5 A	Shielded	50 m (164.04 ft)
Number as transistor	1	Unshielded	150 m (492.13 ft)
Output (resistive load)	DC 30 V, 0.5 A	Standards	
Analog / digital inputs		Compliance with standards	UL, cUL, CE, C-Tick (RCM)
Number	1 (Differential input)		
Resolution	10 bit	CE marking	EMC Directive 2004/108/EC, Low-Voltag Directive 2006/95/EC
Switching threshold as digital in	put		

Analog outputs

0 → 1

1→0

Number 1 (Non-isolated output)

PTC/ KTY interface

1 motor temperature sensor input, sensors that can be connected: PTC, KTY and Thermo-Click, accuracy $\pm 5~^{\circ}\text{C}$

4 V

1.6 V



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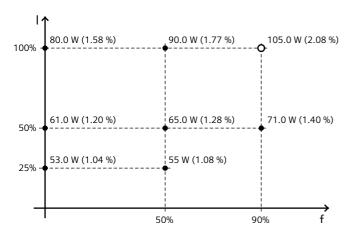
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Figure similar

Converter losses to EN 50598-2*

Efficiency class	IE2
Comparison with the reference converter (90% / 100%)	-69.05 %



The percentage values show the losses in relation to the rated apparent power of the converter.

The diagram shows the losses for the points (as per standard EN 50598) of the relative torque generating current (I) over the relative motor stator frequency(f). The values are valid for the basic version of the converter without options/components.

*converted values