i4-650H/750H/850H

High performance robot for assembly, material handling, and precision machining.

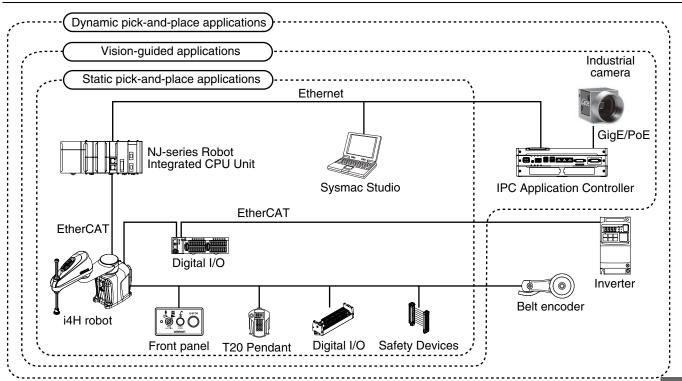
- EtherCAT connectivity to the Omron NJ501-R controller and programming through the familiar IEC 61131-3 programming language or scripting (V+).
- Easy to service with high visibility, multi-colored light ring and LCD display to show the robot status.
- Reach Options of 650 mm, 750 mm, 850 mm with 210 mm or 410 mm z-axis stroke.
- IP65 and Food Grade models available.



Ordering Information

Item	Description	Details	Designation
1	i4H-series		RS4-206
		650 mm	6
2	Reach	750 mm	7
		850 mm	8
3	Mount Configuration	Standard	5
3	Wount Comiguration	Inverted	7
		IP20 (standard)	0
4	Features/Rating	IP65 and Food Grade lubrication	4
		Food Grade lubrication	5
5	Z-axis Quill Stroke Length	210 mm	2 (IP20 and IP65 rating) or 3
3		410 mm	4 (IP20 and IP65 rating) or 5

System configuration



i4H-Series

Specifications

Quill Length 210 mm 410 mm 210 mm 410 mm 210 mm 410 mm Image Appearability at 100% eed XY ±0.015 mm ±0.005° Joint 3 ±0.005° ±0.005° Joint 4 ±152° Joint 2 ±140° Joint 3 210 mm (Standard Quill), 410 mm (Long Quill) ±360° Pertia Moment (Max.) Joint 4 0.5 kg-m² Joint 3 Joint 3 450 deg/s
15 kg ### 20015 mm ### 20005° ### 20005° ### 20015 mm ### 20005° ### 20
Sepentability at 100% Expeatability at 100% Expe
XY
Joint 3
Solit 3
Joint 4
Joint 2
Joint 3 Joint 4 Extra Moment (Max.) Aximum push force - wwward, no load *2 Joint 3 210 mm (Standard Quill), 410 mm (Long Quill) ±360° 0.5 kg-m² 588 N
Joint 3 Joint 4 ±360° Pertia Moment (Max.) Joint 4 0.5 kg-m² Saximum push force - Swnward, no load *2 Joint 3 210 mm (Standard Quill), 410 mm (Long Quill) ±360° 0.5 kg-m² 588 N
ertia Moment (Max.) Joint 4 0.5 kg-m² sximum push force - bwnward, no load *2 Joint 3 588 N
aximum push force - Joint 3 588 N
wnward, no load *2 Joint 3 588 N
Joint 1 450 deg/s
int Speeds 720 deg/s
Joint 3 1583 mm/s
Joint 4 2400 deg/s
Burst *4 0.41 s 0.39 s 0.39 s
Sustained 0.45 s 0.46 s 0.50 s
Blended Burst *4 0.32 s 0.31 s 0.31 s
ower Requirements DC 24 VDC ±10%, 8 A max.
200 to 240 VAC, 50/60 Hz, Single Phase, 12.0 A max.
IP20, Standard Model IP20 / NEMA Type 1
IP20, Food GradeIP20 / NEMA Type 1, Food Grade LubricationotectionModelNSF H1, ISO 21469 certified
IP65 / NEMA Type 4, Food Grade Lubrication NSF H1, ISO 21469 certified
Dunting Table, Inverted, Wall
vironment Ambient Temperature 0° to 40°C
equirements Humidity Range 5% to 90% non-condensing
Standard and Inverted 50.4 kg 50.8 kg 50.9 kg 51.3 kg 51.6 kg 52.0 kg
Standard and Inverted IP65 52.9 kg 53.3 kg 53.4 kg 53.8 kg 54.1 kg 54.5 kg
Inputs 12 sinking/sourcing inputs, 0 to 30 VDC
Outputs 8 sourcing outputs, 24 VDC ±10%, 0.7 A per output 1.5 A max. @ 25°C for all circuits
nd-of-Arm EtherCAT port 1 (4 pin, M12 female)
ectrical pass-through ports 2 (19 pin, M23 male)
eumatic pass-through ports 4 (6 mm, push-type fittings) max. pressure 0.55 MPa
onveyor tracking inputs 2
6-232C serial communication ports 1
ogramming Software Sysmac Studio 64-bit
obot Vision Manager Yes
ckManager Yes
equired Controller OMRON NJ501-R Series

^{*1} Payload includes any object(s) attached to a robot link or tool flange, including end-effectors, tooling, valves, grippers, and objects being handled by the robot.

^{*2} At a duty cycle of 3 seconds pushing and then 2 seconds not pushing.

^{*3} Cycle time is defined as a continuous path with straight-line motion in which the robot tool moves up 25 mm, laterally 305 mm, down 25 mm, and then back along the same path (not achievable over all paths in the robot working envelope). Values listed are with no joint 4 rotation, at 20°C ambient with a 2.0 kg payload. Blended Burst cycle uses the same criteria with arc motion.

^{*4} Burst and Blended Burst cycle times may increase by up to 15% when using IP65-rated robots.

Options and Additional Items

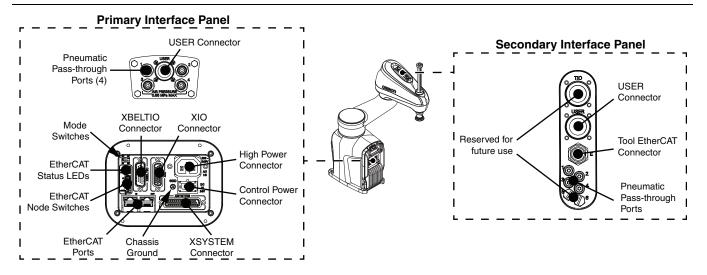
Item	Description	Details	Part Number
XSYSTEM Cable with	Provides connections for a Front Panel, Teach	1.8 m cable length.	13323-100*1
jumpers	Peridant, and other user-supplied devices.		
Cable Seal Kit, Standard Cable Seal Kit, Inverted	Cable Seal for all cable connections at the Primary Interface Panel.	All components for replacing or installing a cable seal included.	08765-000*2 08765-200*2
High Power Connector	Used to supply 200 to 240 VAC power for the internal servo amplifiers.	Includes connector, pins, and retaining clip.	22822-100 ^{*1}
Control Power Connector	Used to supply 24 VDC control power.	Includes connector and pins.	22822-200*1
XBELTIO Cable	Provides connections to Belt Encoder, EXPIO, and RS-232 signals.	0.6 m cable length.	13463-000
XIO Breakout Cable	Provides a flying leads connection to digital I/O at the XIO connector on the robot.	5 m cable length.	04465-000
XIO Termination Block and Cable	Provides terminal block digital I/O connections at the XIO connector on the robot.	Includes a terminal block with a 1.8 m cable.	90356-40100
IO Blox Kit	Provides additional I/O (8 inputs and 8 outputs).	Includes an IO Blox unit with a 0.3 m cable.	90356-30200
IO Blox Expansion Kit	Provides IO Blox unit expansion.	Includes an IO Blox unit with a 0.3 m cable.	90356-30100
IO Blox Extension Cable	Extends the length between two IO Blox units.	3 m cable length.	04679-030
IO Blox Extension Cable	Extends the length between an IO Blox unit and a robot.	3 m cable length.	04677-030
Encoder Kit	Includes all equipment to add an encoder to a robot.	Includes encoder, mounting bracket, and 5 m cable.	09742-001
Encoder Extension Cable	Replaces or extends the Encoder Kit cable.	5 m cable length.	09446-050
Belt Encoder Y-adapter Cable	Provides two M12 connectors for the Belt Encoder signals/connector on the XSYSTEM cable.	3 m cable length.	09443-000
Electrical Pass-through Ports Cable	Provides flying leads for USER ports on the Primary and Secondary Interface Panels.	1.7 m cable length.	18823-100
Front Panel Kit	Front Panel with extension cable for connection to the XFP connector on the XSYSTEM cable.	Includes a Front Panel with a 3 m cable.	92546-10358 ^{*1}
eCobra Mount Adapter			21636-000
eCobra Tool Flange			19106-100F
Tool Flange	Replacement tool flange for i4H robot.		19106-000F*1
Camera Mounting Bracket	Used to mount a camera to the outer link.		18908-000
Camera Mounting Adapter			22295-000
T20 Pendant Kit	Provides all required equipment for the T20 Pendant.	Includes the T20 Pendant, 3 m adapter cable, and a jumper plug.	10046-010
IPC Application Controller	Used to execute PackManager and Robot Vision Manager applications.	Refer to catalog P072 for more information.	AC1-152000
Wall Mount Bracket	Enables mounting the robot to a vertical surface.	Not compatible with IP65-rated robots.	20089-000
NJ501-R Series Robotics Integrated Controller	Machine controller with sequence, motion, and robotics functionality.	Refer to catalog P072 for more information.	NJ501-R□□□
Sysmac Studio	Settings and creation of programs to control a robot with the Robot Integrated CPU Unit and IPC Application Controller.	A license for the Standard Edition (SYSMAC-SE201L) is required.	SYSMAC- SE200D-64
3D Simulation	Perform 3D simulation including robots and periph	eral devices.	SYSMAC- SA401L-64
PackManager	Enables full functionality of the PackManager softv	vare.	20409-000
Robot Vision Manager	Enables the Robot Vision Manager functionality and inspection tools library.		20410-000
PackManager + Robot Vision Manager	iger + Robot Enables functionality of both PackManager and Robot Vision Manager		20433-000
Bellows Installation Kit	Two bellows and associated hardware for	210 mm quill length.	19464-003F*2
Bellows Installation Kit	protecting the quill.	410 mm quill length.	19464-004F*2
Bellows Replacement Kit	Upper and lower replacement bellows.	210 mm quill length.	19464-103F
Bellows Replacement Kit	opper and lower replacement bellows.	410 mm quill length.	19464-104F

i4H-Series

Item	Description	Details	Part Number
Encoder Backup Battery Pack	Includes two 3.6 V batte	ries.	19238-000F*1

^{*1} Supplied with all robots.

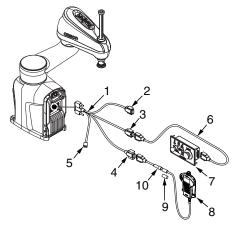
Interface Panels



Cables and Connections

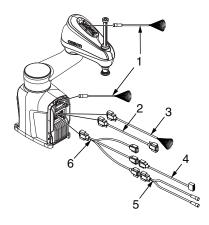
Refer to Options and Accessories for more information.

Standard Cables and Connections



Item	Description	Function	Part Number	
1	XSYSTEM Cable	Main interface cable.		
2	XUSR Connector	User-supplied safety devices.		
3	XFP Connector	Front Panel connections.	13322-100	
4	Ethernet Connector	Service mode connection.		
5	XMCP Connector	T20 Pendant.		
6	Front Panel Extension Cable		00540 10050	
7	Front Panel	High-power, mode, and E-stop.	92546-10358	
8	T20 Pendant			
9	T20 Pendant Jumper Plug	Used when T20 Pendant is not connected.	10046-010	
10	T20 Pendant Adapter Cable)		

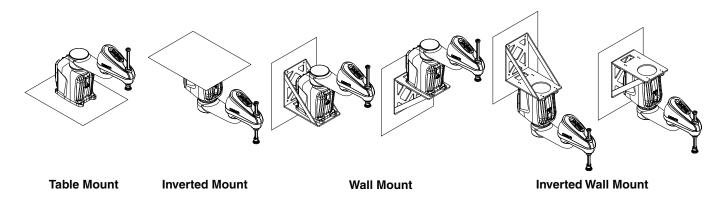
Optional Cables and Connections



Item	Description	Function	Part Number
1	USER Connector Cables	Pass-through electrical signals.	18823-100
2	XIO Termination Block Cable	Connection to I/O termination block.	03695-000
3	XIO Breakout Cable	I/O flying leads.	04465-000
4	EXPIO to IO Blox Cable	IO Blox connections.	04677-030
5	Belt Encoder Y-adapter Cable	Direct encoder connections.	09443-000
6	XBELTIO Adapter Cable	Encoder, force, and RS-232 signal interface cable.	13463-000

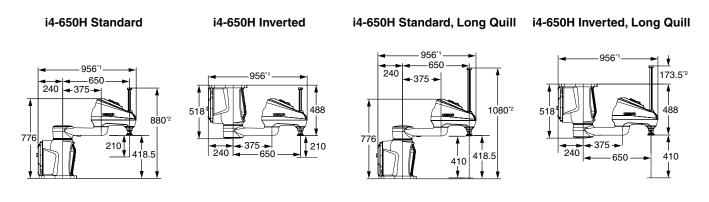
^{*2} Supplied with IP65 rated robots.

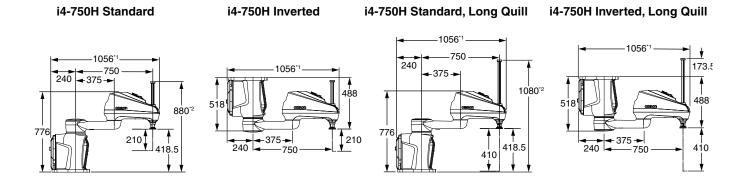
Mounting Options

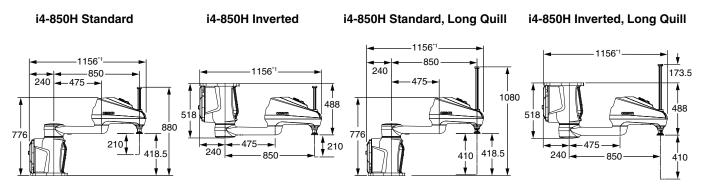


Robot Dimensions

(Unit: mm)

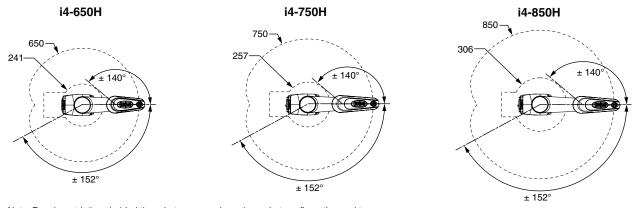






^{*1} The overall length increases by 150 mm if a cable seal box is installed.

^{*2} The overall height of the robot increases by 47 mm if bellows are installed. Note: The base of the robot is 240 mm wide.

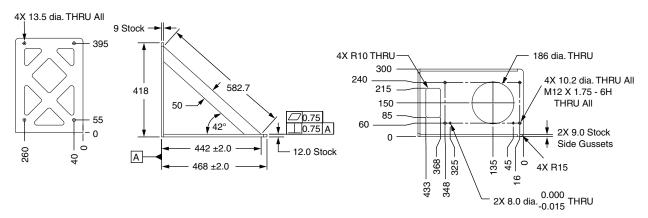


Note: Reach restrictions behind the robot may vary based on robot configuration and type.

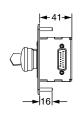
Other Dimensions

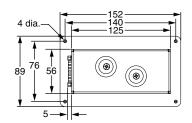
(Unit: mm)

Wall Mount Bracket

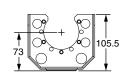


Front Panel



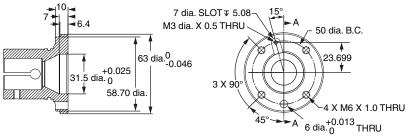


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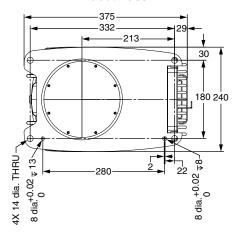


Camera Mounting Bracket

Tool Flange

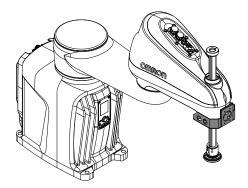


Robot Base

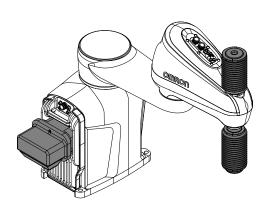


Other Information

Camera Bracket



Cable Seal Kit and Bellows (IP65)



Related Manuals

Catalog Number	Manual Title
1590	Robot Safety Guide
I601	T20 Pendant User's Manual
I661	i4H Robots with EtherCAT User's Manual
1632	IPC Application Controller User's Manual
I671	NeVp User's Manual
1672	NeVp Keyword Reference Manual
O037	NJ-series Robot Integrated CPU Unit User's Manual
O049	Machine Automation Controller NJ-series Robot Integrated System Startup Guide
W504	Sysmac Studio Version 1 Operation Manual
W595	Sysmac Studio Robot Integrated System Building Function with Robot Integrated CPU Unit Operation Manual
W618	Sysmac Studio 3D Simulation Function Operation Manual
W621	Sysmac Studio Robot Integrated System Building Function with IPC Application Controller Operation Manual

MEMO

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OMRON Corporation Industrial Automation Company

Kyoto, JAPAN

Contact: www.ia.omron.com

Regional Headquarters

Ognon EUROPE B.V.
Wegalaan 67-69, 2132 JD Hoofddorp
The Netherlands
Tel: (31)2356-81-300/Fax: (31)2356-81-388

OMRON ASIA PACIFIC PTE. LTD.
No. 438A Alexandra Road # 05-05/08 (Lobby 2),
Alexandra Technopark,
Singapore 119967
Tel: (65) 6835-3011/Fax: (65) 6835-2711

OMRON ELECTRONICS LLC 2895 Greenspoint Parkway, Suite 200 Hoffman Estates, IL 60169 U.S.A. Tel: (1) 847-843-7900/Fax: (1) 847-843-7787

OMRON ROBOTICS AND SAFETY TECHNOLOGIES, INC. 4225 Hacienda Dr., Pleasanton, CA 94588 U.S.A. Tel: (1) 925-245-3400/Fax: (1) 925-960-0590

OMRON (CHINA) CO., LTD.
Room 2211, Bank of China Tower, 200 Yin Cheng Zhong Road, PuDong New Area, Shanghai, 200120, China
Tel: (86) 21-5037-2222/Fax: (86) 21-5037-2200

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