




**Variable frequency drive, 400 V AC, 3-phase, 140 A, 75 kW, IP54/NEMA12,  
Brake chopper, DC link choke**



**Part no. DG1-34140FB-C54C**  
**Catalog No. 9702-5105-00P**  
**Alternate Catalog No. DG1-34140FB-C54C**  
**EL-Nummer 4138109**  
**(Norway)**

**Delivery program**

Photo			
Product range			Variable frequency drives
Part group reference (e.g. DIL)			DG1
Rated operational voltage	U <sub>e</sub>		400 V AC, 3-phase 480 V AC, 3-phase 500 V AC, 3-phase
Output voltage with V <sub>e</sub>	U <sub>2</sub>		400 V AC, 3-phase 480 V AC, 3-phase 500 V AC, 3-phase
Mains voltage (50/60Hz)	U <sub>LN</sub>	V	380 (-15%) - 500 (+10%)
<b>Rated operational current</b>			
At 150% overload	I <sub>e</sub>	A	140
At 110% overload	I <sub>e</sub>	A	170
Note			Rated operational current for a switching frequency of 1 - 10 kHz and an ambient temperature of +50 °C for a 150% overload and +40 °C for a 110% overload
<b>Assigned motor rating</b>			
Note			for normal internally and externally ventilated 4 pole, three-phase asynchronous motors with 1500 rpm <sup>-1</sup> at 50 Hz or 1800 min <sup>-1</sup> at 60 Hz
Note			Overload cycle for 60 s every 600 s
Note			at 400 V, 50 Hz
150 % Overload	P	kW	75
110 % Overload	P	kW	90
150 % Overload	I <sub>M</sub>	A	134
110 % Overload	I <sub>M</sub>	A	161
Note			at 500 V, 50 Hz
150 % Overload	P	kW	90
110 % Overload	P	kW	110
150 % Overload	I <sub>M</sub>	A	129
110 % Overload	I <sub>M</sub>	A	157
Note			at 480 V, 60 Hz
150 % Overload	P	HP	100
110 % Overload	P	HP	125
150 % Overload	I <sub>M</sub>	A	124
110 % Overload	I <sub>M</sub>	A	156
Degree of Protection			IP54/NEMA12
Interface/field bus (built-in)			Modbus RTU Modbus TCP BACnet MS/TP Ethernet IP
Fieldbus connection (optional)			PROFIBUS CANopen® DeviceNet SmartWire-DT
Fitted with			Radio interference suppression filter

			Additional PCB protection Multi-line graphic display Brake chopper DC link choke
Parameterization			Keypad Fieldbus Power Xpert inControl
Frame size			FS5
Connection to SmartWire-DT			yes in conjunction with DXG-NET-SWD SmartWire DT module

## Technical data

### General

Standards			Specification for general requirements: IEC/EN 61800-2 EMC requirements: IEC/EN 61800-3 Safety requirements: IEC/EN 61800-5
Certifications			CE, UL, cUL, c-Tick, UkrSEPRO, EAC
Production quality			RoHS, ISO 9001
Climatic proofing	$\rho_w$	%	< 95%, average relative humidity (RH), non-condensing, non-corrosive
Air quality			3C2, 3S2
Ambient temperature			
Operating ambient temperature min.		°C	-10
Operating ambient temperature max.		°C	+ 50
operation (110 % overload)	$\theta$	°C	-10 - +40
			Operation with 110 % overload (1 min./10 min.): -10 to +40 (max. +55 with 1% derating per Kelvin above limit) Operation with 150% overload (1 min./10 min.): -10 to +50 (max. +60 with 1% derating per Kelvin above limit) -20 with cold-weather mode
Storage	$\theta$	°C	-40 - +70
Overvoltage category			III
Pollution degree			2
Radio interference level			
Radio interference class (EMC)			C1 (with external filter, for conducted emissions only), C2, C3, depending on the motor cable length, the connected load, and ambient conditions. External radio interference suppression filters (optional) may be necessary.
Environment (EMC)			1st and 2nd environments as per EN 61800-3
maximum motor cable length	l	m	C2 ≤ 10 m C3 ≤ 50 m
Mechanical shock resistance		g	EN 61800-5-1, EN 60068-2-27 UPS drop test (for weights inside the UPS frame) Storage and transportation: maximum 15 g, 11 ms (inside the packaging)
Vibration			EN 61800-5-1, EN 60068-2-6: 5 - 150 Hz Amplitude: 1 mm (peak) at 5 - 15.8 Hz Maximum acceleration amplitude: 1 g at 15.8 – 150 Hz
Mounting position			Vertical
Altitude		m	0 - 1000 m above sea level Above 1000 m: 1% derating for every 100 m max. 3000 m (2000 m for Corner Grounded TN Systems)
Degree of Protection			IP54/NEMA12
Protection against direct contact			BGV A3 (VBG4, finger- and back-of-hand proof)

### Main circuit

Supply			
Rated operational voltage	$U_e$		400 V AC, 3-phase 480 V AC, 3-phase 500 V AC, 3-phase
Mains voltage (50/60Hz)	$U_{LN}$	V	380 (-15%) - 500 (+10%)
Input current (150% overload)	$I_{LN}$	A	129
Input current (110% overload)	$I_{LN}$	A	157
System configuration			TN-S, TN-C, TN-C-S, TT, IT
Supply frequency	$f_{LN}$	Hz	50/60
Frequency range	$f_{LN}$	Hz	45–66 (± 0%)
Mains switch-on frequency			Maximum of one time every 60 seconds
Mains current distortion	THD	%	29.5
Rated conditional short-circuit current	$I_q$	kA	< 100

<b>Power section</b>			
Function			Variable frequency drive with internal DC link, DC link choke and IGBT inverter
Overload current (150% overload)	$I_L$	A	210
Overload current (110% overload)	$I_L$	A	187
max. starting current (High Overload)	$I_H$	%	200
Note about max. starting current			for 2 seconds every 20 seconds
Output voltage with $V_e$	$U_2$		400 V AC, 3-phase 480 V AC, 3-phase 500 V AC, 3-phase
Output Frequency	$f_2$	Hz	0 - 50/60 (max. 400)
Switching frequency	$f_{PWM}$	kHz	3.6 adjustable 1 - 10
Operation Mode			U/f control Speed control with slip compensation sensorless vector control (SLV) Torque regulation
Frequency resolution (setpoint value)	$\Delta f$	Hz	0.01
Rated operational current			
At 150% overload	$I_e$	A	140
At 110% overload	$I_e$	A	170
Note			Rated operational current for a switching frequency of 1 - 10 kHz and an ambient temperature of +50 °C for a 150% overload and +40 °C for a 110% overload
Motor current limit	$I$	A	$0.1 - 2 \times I_H$ (CT)
Power loss			
Heat dissipation at rated operational current $I_e = 150\%$	$P_V$	W	1289
Heat dissipation at rated operational current $I_e = 110\%$	$P_V$	W	1594
Efficiency	$\eta$	%	98.6
Maximum leakage current to ground (PE) without motor	$I_{PE}$	mA	7.5
Fan			temperature controlled externally accessible
Internal fan delivery rate		$m^3/h$	395
Fitted with			Radio interference suppression filter Additional PCB protection Multi-line graphic display Brake chopper DC link choke
Safety function			STO (Safe Torque Off, SIL1, PLc Cat 1)
Frame size			FS5
<b>Motor feeder</b>			
Note			for normal internally and externally ventilated 4 pole, three-phase asynchronous motors with $1500 \text{ rpm}^{-1}$ at 50 Hz or $1800 \text{ min}^{-1}$ at 60 Hz
Note			Overload cycle for 60 s every 600 s
Note			at 400 V, 50 Hz
150 % Overload	P	kW	75
110 % Overload	P	kW	90
Note			at 500 V, 50 Hz
150 % Overload	P	kW	90
110 % Overload	P	kW	110
Note			at 480 V, 60 Hz
150 % Overload	P	HP	100
110 % Overload	P	HP	125
maximum permissible cable length	$l$	m	screened: 200
Apparent power			
Apparent power at rated operation 400 V	S	kVA	117.8
Apparent power at rated operation 480 V	S	kVA	147.2
Braking function			
Standard braking torque			max. 30 % $M_N$
DC braking torque			adjustable to 150 %
Braking torque with external braking resistance			Max. 100% of rated operational current $I_e$ with external braking resistor

minimum external braking resistance	$R_{min}$	$\Omega$	3.3
Switch-on threshold for the braking transistor	$U_{DC}$	V	850 V DC
DC braking	%	$I/I_e$	$\leq 150$ , adjustable

### Control section

External control voltage	$U_c$	V	24 V DC (max. 250 mA options incl.)
Reference voltage	$U_s$	V	10 V DC (max. 10 mA)
Analog inputs			2, parameterizable, 0 - 10 V DC, 2 - 10 V DC, -10 - +10 V DC, 0/4 - 20 mA
Analog outputs			2, parameterizable, 0 - 10 V, 0/4 - 20 mA
Digital inputs			8, parameterizable, max. 30 V DC
Digital outputs			1, parameterizable, 24 V DC
Relay outputs			3, parameterizable, 2 changeover contacts and 1 N/O, 6 A (240 VAC) / 6 A (24 VDC)
Interface/field bus (built-in)			Modbus RTU Modbus TCP BACnet MS/TP Ethernet IP
Expansion slots			2

### Assigned switching and protective elements

Power Wiring			
Safety device (fuse or miniature circuit-breaker)			
IEC (Type B, gG), 150 %			NZMC1-A160
IEC (Type B, gG), 110 %			NZMC2-A200
UL (Class CC or J)		A	200
Mains contactor			
150 % overload (CT/I <sub>H</sub> , at 50 °C)			DILM150
110 % overload (VT/I <sub>L</sub> , at 40 °C)			DILM170...
Main choke			
150 % overload (CT/I <sub>H</sub> , at 50 °C)			Integrated DC link choke, uk = 5%
110 % overload (VT/I <sub>L</sub> , at 40 °C)			Integrated DC link choke, uk = 5%
Radio interference suppression filter (external, 150 %)			DX-EMC34-130
Radio interference suppression filter (external, 110 %)			DX-EMC34-180
Radio interference suppression filter, low leakage currents (external, 150 %)			DX-EMC34-130-L
Radio interference suppression filter, low leakage currents (external, 110 %)			DX-EMC34-180-L
Note regarding radio interference suppression filter			Optional external radio interference suppression filter for longer motor cable lengths and for use in different EMC environments
DC link connection			
Braking resistance			
10 % duty factor (DF)			P:3 x DX-BR012-9K2
20 % duty factor (DF)			P:3 x DX-BR012-18K1
40 % duty factor (DF)			P:3 x DX-BR012-18K1
Notes concerning braking resistances:			P:n = "n" resistors connected in parallel The brake resistors are assigned based on the maximum rated power of the variable frequency drive. Additional brake resistors and designs (e.g. different duty cycles) are available upon request.
Motor feeder			
motor choke			
150 % overload (CT/I <sub>H</sub> , at 50 °C)			DX-LM3-150
110 % overload (VT/I <sub>L</sub> , at 40 °C)			DX-LM3-180
Sine filter			
150 % overload (CT/I <sub>H</sub> , at 50 °C)			DX-SIN3-150
110 % overload (VT/I <sub>L</sub> , at 40 °C)			DX-SIN3-180
All-pole sine filter			
150 % overload (CT/I <sub>H</sub> , at 50 °C)			P:2 x DX-SIN3-110-A
110 % overload (VT/I <sub>L</sub> , at 40 °C)			P:2 x DX-SIN3-110-A

### Design verification as per IEC/EN 61439

Technical data for design verification			
Rated operational current for specified heat dissipation	$I_n$	A	140

Heat dissipation per pole, current-dependent	P <sub>vid</sub>	W	0
Equipment heat dissipation, current-dependent	P <sub>vid</sub>	W	1594
Static heat dissipation, non-current-dependent	P <sub>vs</sub>	W	30.74
Heat dissipation capacity	P <sub>diss</sub>	W	0
Operating ambient temperature min.		°C	-10
Operating ambient temperature max.		°C	50
Operation (with 150 % overload), allow for derating			
IEC/EN 61439 design verification			
10.2 Strength of materials and parts			
10.2.2 Corrosion resistance			
Meets the product standard's requirements.			
10.2.3.1 Verification of thermal stability of enclosures			
Meets the product standard's requirements.			
10.2.3.2 Verification of resistance of insulating materials to normal heat			
Meets the product standard's requirements.			
10.2.3.3 Verification of resistance of insulating materials to abnormal heat and fire due to internal electric effects			
Meets the product standard's requirements.			
10.2.4 Resistance to ultra-violet (UV) radiation			
Meets the product standard's requirements.			
10.2.5 Lifting			
Does not apply, since the entire switchgear needs to be evaluated.			
10.2.6 Mechanical impact			
Does not apply, since the entire switchgear needs to be evaluated.			
10.2.7 Inscriptions			
Meets the product standard's requirements.			
10.3 Degree of protection of ASSEMBLIES			
Does not apply, since the entire switchgear needs to be evaluated.			
10.4 Clearances and creepage distances			
Meets the product standard's requirements.			
10.5 Protection against electric shock			
Does not apply, since the entire switchgear needs to be evaluated.			
10.6 Incorporation of switching devices and components			
Does not apply, since the entire switchgear needs to be evaluated.			
10.7 Internal electrical circuits and connections			
Is the panel builder's responsibility.			
10.8 Connections for external conductors			
Is the panel builder's responsibility.			
10.9 Insulation properties			
10.9.2 Power-frequency electric strength			
Is the panel builder's responsibility.			
10.9.3 Impulse withstand voltage			
Is the panel builder's responsibility.			
10.9.4 Testing of enclosures made of insulating material			
Is the panel builder's responsibility.			
10.10 Temperature rise			
The panel builder is responsible for the temperature rise calculation. Eaton will provide heat dissipation data for the devices.			
10.11 Short-circuit rating			
Is the panel builder's responsibility. The specifications for the switchgear must be observed.			
10.12 Electromagnetic compatibility			
Is the panel builder's responsibility. The specifications for the switchgear must be observed.			
10.13 Mechanical function			
The device meets the requirements, provided the information in the instruction leaflet (IL) is observed.			

## Technical data ETIM 7.0

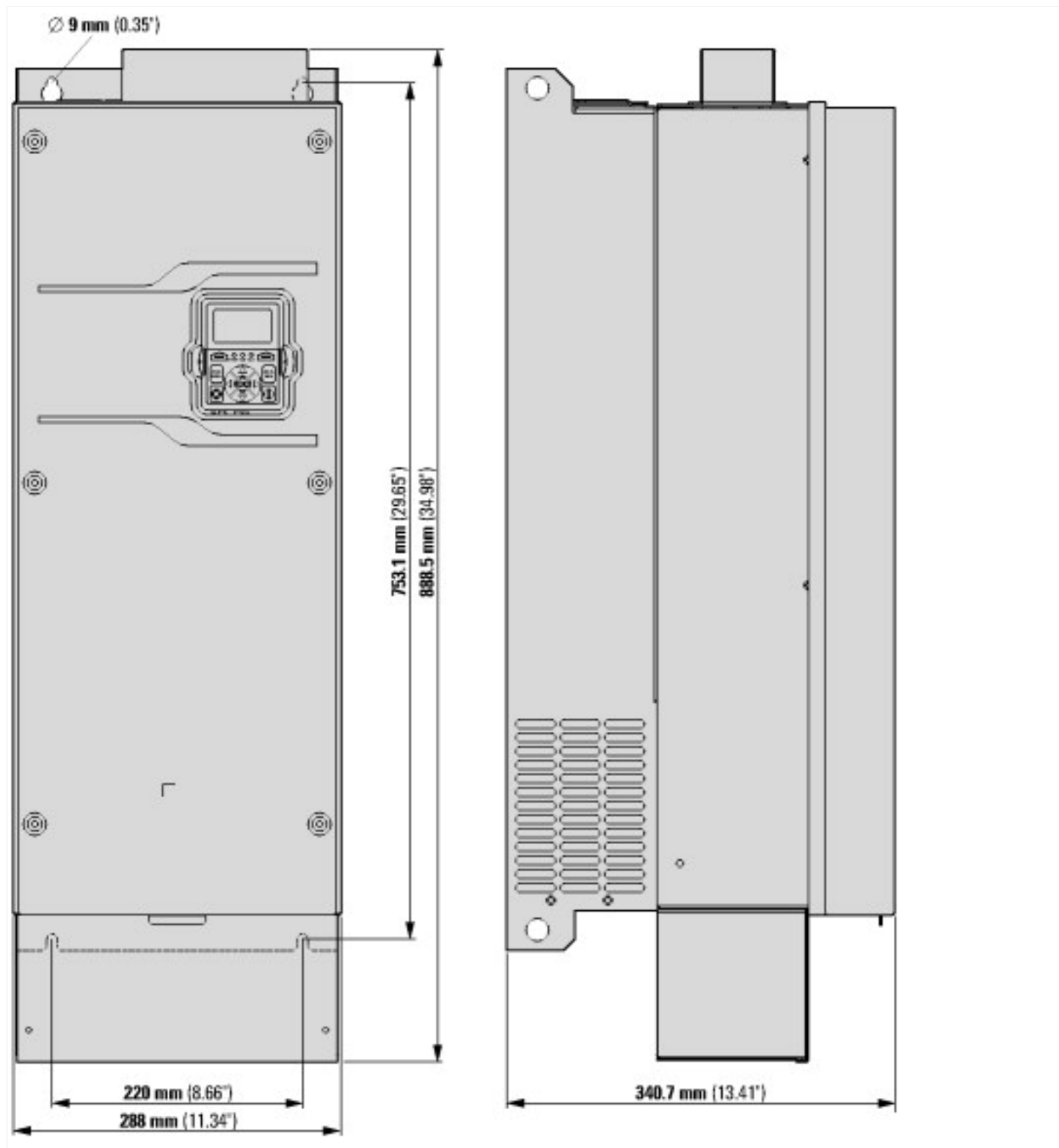
Low-voltage industrial components (EG000017) / Frequency converter =< 1 kV (EC001857)			
Electric engineering, automation, process control engineering / Electrical drive / Static frequency converter / Static frequency converter = < 1 kV (ecI@ss10.0.1-27-02-31-01 [AKE177014])			
Mains voltage		V	323 - 550
Mains frequency			50/60 Hz
Number of phases input			3
Number of phases output			3
Max. output frequency		Hz	400
Max. output voltage		V	480
Nominal output current I <sub>2N</sub>		A	170
Max. output at quadratic load at rated output voltage		kW	90
Max. output at linear load at rated output voltage		kW	150
Relative symmetric net frequency tolerance		%	10
Relative symmetric net voltage tolerance		%	10
Number of analogue outputs			2
Number of analogue inputs			2
Number of digital outputs			1
Number of digital inputs			8
With control unit			Yes
Application in industrial area permitted			Yes

Application in domestic- and commercial area permitted		Yes
Supporting protocol for TCP/IP		Yes
Supporting protocol for PROFIBUS		Yes
Supporting protocol for CAN		Yes
Supporting protocol for INTERBUS		No
Supporting protocol for ASI		No
Supporting protocol for KNX		No
Supporting protocol for MODBUS		Yes
Supporting protocol for Data-Highway		No
Supporting protocol for DeviceNet		Yes
Supporting protocol for SUCONET		No
Supporting protocol for LON		No
Supporting protocol for PROFINET IO		Yes
Supporting protocol for PROFINET CBA		No
Supporting protocol for SERCOS		No
Supporting protocol for Foundation Fieldbus		No
Supporting protocol for EtherNet/IP		Yes
Supporting protocol for AS-Interface Safety at Work		No
Supporting protocol for DeviceNet Safety		No
Supporting protocol for INTERBUS-Safety		No
Supporting protocol for PROFIsafe		No
Supporting protocol for SafetyBUS p		No
Supporting protocol for BACnet		Yes
Supporting protocol for other bus systems		Yes
Number of HW-interfaces industrial Ethernet		1
Number of interfaces PROFINET		0
Number of HW-interfaces RS-232		0
Number of HW-interfaces RS-422		0
Number of HW-interfaces RS-485		1
Number of HW-interfaces serial TTY		0
Number of HW-interfaces USB		0
Number of HW-interfaces parallel		0
Number of HW-interfaces other		1
With optical interface		No
With PC connection		Yes
Integrated breaking resistance		Yes
4-quadrant operation possible		Yes
Type of converter		U converter
Degree of protection (IP)		IP54
Degree of protection (NEMA)		12
Height	mm	888
Width	mm	290
Depth	mm	344

## Approvals

Product Standards		UL508C, CSA-C22.2 No. 274-13; IEC/EN61800-3; IEC/EN61800-5; CE marking
UL File No.		E134360
UL Category Control No.		NMMS, NMMS7
CSA File No.		UL report applies to both US and Canada
North America Certification		UL listed, certified by UL for use in Canada
Suitable for		Branch circuits
Max. Voltage Rating		3~500 V AC IEC: TN-S UL/CSA: 'Y' (Solidly Grounded Wey)
Degree of Protection		IP54/NEMA12

## Dimensions



## Additional product information (links)

Documentation	<a href="http://www.eaton.eu/Europe/Electrical/ProductsServices/AutomationControl/SwitchingProtectingDrivingMotors/PowerXLfrequencydrives/DG1GeneralPurposeDrives/index.htm?wtredirect=www.eaton.eu/dg1#tabs-7">http://www.eaton.eu/Europe/Electrical/ProductsServices/AutomationControl/SwitchingProtectingDrivingMotors/PowerXLfrequencydrives/DG1GeneralPurposeDrives/index.htm?wtredirect=www.eaton.eu/dg1#tabs-7</a>
Manuals	<a href="http://www.eaton.eu/Europe/Electrical/ProductsServices/AutomationControl/SwitchingProtectingDrivingMotors/PowerXLfrequencydrives/DG1GeneralPurposeDrives/index.htm?wtredirect=www.eaton.eu/dg1#tabs-8">http://www.eaton.eu/Europe/Electrical/ProductsServices/AutomationControl/SwitchingProtectingDrivingMotors/PowerXLfrequencydrives/DG1GeneralPurposeDrives/index.htm?wtredirect=www.eaton.eu/dg1#tabs-8</a>