

Variable frequency drive, 230 V AC, 3-phase, 25 A, 5.5 kW, IP20/NEMA0, Brake chopper



Part no. Catalog No. DM1-32025NB-N20B-EM

3-5022-002A

EL-Nummer (Norway) 4132286

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Delivery program

| Delivery program | | | |
|------------------------------------|----------------|----|---|
| Product range | | | Variable frequency drives |
| Part group reference (e.g. DIL) | | | DM1 |
| | | | IE2 ✓ |
| Rated operational voltage | U _e | | 230 V AC, 3-phase 240 V AC, 3-phase |
| Output voltage with V _e | U ₂ | | 230 V AC, 3-phase 240 V AC, 3-phase |
| Mains voltage (50/60Hz) | U_{LN} | V | 208 (-10%) - 240 (+10%) |
| Rated operational current | | | |
| At 150% overload | I _e | Α | 25 |
| At 110% overload | I _e | Α | 32 |
| Note | | | Rated operational current for a switching frequency of 1 - 16 kHz and an ambient temperature of +50 °C for a 150% overload and +40 °C for a 110% overload |
| Assigned motor rating | | | |
| Note | | | for normal internally and externally ventilated 4 pole, three-phase asynchronous motors with 1500 rpm ⁻¹ at 50 Hz or 1800 min ⁻¹ at 60 Hz for PM motors |
| Note | | | Overload cycle for 60 s every 600 s |
| Note | | | at 230 V, 50 Hz |
| 150 % Overload | Р | kW | 5.5 |
| 110 % Overload | P | kW | 7.5 |
| 150 % Overload | I _M | Α | 19.6 |
| 110 % Overload | I _M | Α | 26.4 |
| Note | | | at 230 V, 60 Hz |
| 150 % Overload | P | HP | 7.5 |
| 110 % Overload | P | HP | 10 |
| 150 % Overload | I _M | Α | 22 |
| 110 % Overload | I_{M} | Α | 28 |
| Degree of Protection | | | IP20/NEMA0 |
| Interface/field bus (built-in) | | | Modbus RTU |
| Fieldbus connection (optional) | | | Profibus, CAN, DeviceNet, SmartwireDT |
| Fitted with | | | Brake chopper |
| Parameterization | | | Keypad Fieldbus Power Xpert inControl |
| Frame size | | | FS3 |
| Connection to SmartWire-DT | | | yes in conjunction with DXG-NET-SWD SmartWire DT module |

Technical data

Genera

| delleral | |
|--------------------|---|
| Standards | General requirements: IEC/EN 61800-2 EMV requirements: IEC/EN 61800-3 Safety requirements: IEC/EN 61800-5-1:2007/A1:2017; UL 61800-5-1:2012 (Rev. 2018), CSA C22.2 No. 274-17:2017 |
| Certifications | CE, UL, cUL, c-Tick, UkrSEPRO, EAC |
| Production quality | RoHS, ISO 9001 |

| Climatic proofing | ρ_{W} | % | < 95%, average relative humidity (RH), non-condensing, non-corrosive |
|---|-------------------|-----|---|
| Air quality | | | 3C2, 3S2 |
| Ambient temperature | | | |
| Operating ambient temperature min. | | °C | -10 |
| Operating ambient temperature max. | | °C | + 50 |
| operation (110 % overload) | θ | °C | -10 - +40 (max. +55 with 1 % derating per Kelvin temperature rise) °C |
| | | | Operation with 110 % overload (1 min./10 min.): -10 to +40 (max. +55 with 1% derating per Kelvin above limit) Operation with 150% overload (1 min./10 min.): -10 to +50 (max. +60 with 1% derating per Kelvin above limit) -20 with cold-weather mode |
| Storage | 9 | °C | -40 - +70 |
| Overvoltage category | | | III |
| Pollution degree | | | 2 |
| Radio interference level | | | |
| Radio interference class (EMC) | | | C1 (with external filter, for conducted emissions only), C2, C3, depending on the motor cable length, the connected load, and ambient conditions. External radio interference suppression filters (optional) may be necessary. |
| Environment (EMC) | | | 1st and 2nd environments as per EN 61800-3 |
| Mechanical shock resistance | | g | EN 61800-5-1, EN 60068-2-6: 10 - 150 Hz Amplitude: 0,75 mm (peak) bei 10 - 57 Hz Maximum acceleration amplitude: 1 g at 57 — 150 Hz |
| Mounting position | | | Vertical |
| Altitude | | m | 0 - 1000 m above sea level Above 1000 m: 1% derating for every 100 m max. 3000 m (2000 m for Corner Grounded TN Systems) |
| Degree of Protection | | | IP20/NEMA0 |
| Protection against direct contact | | | BGV A3 (VBG4, finger- and back-of-hand proof) |
| Main circuit | | | |
| Supply Rated operational voltage | U _e | | 230 V AC, 3-phase 240 V AC, 3-phase |
| Mains voltage (50/60Hz) | U_{LN} | V | 208 (-10%) - 240 (+10%) |
| Input current (150% overload) | I _{LN} | Α | 29.1 |
| Input current (110% overload) | I _{LN} | Α | 37 |
| System configuration | | | TN-S, TN-C, TN-C-S, TT, IT |
| Supply frequency | f _{LN} | Hz | 50/60 |
| Frequency range | f _{LN} | Hz | 45–66 (± 0%) |
| Mains switch-on frequency | | | Maximum of one time every 60 seconds |
| Mains current distortion | THD | % | 40 |
| Rated conditional short-circuit current | Iq | kA | < 100 |
| Power section | | | |
| Function | | | Variable frequency drive with internal DC link, DC link choke and IGBT inverter |
| Overload current (150% overload) | IL | Α | 37.5 |
| Overload current (110% overload) | IL | Α | 35.2 |
| max. starting current (High Overload) | I _H | % | 200 |
| Note about max. starting current | | | for 2 seconds every 20 seconds |
| Output voltage with V _e | U ₂ | | 230 V AC, 3-phase 240 V AC, 3-phase |
| Output Frequency | f ₂ | Hz | 0 - 50/60 (max. 400) |
| Switching frequency | f _{PWM} | kHz | 4 adjustable 1 - 16 |
| Operation Mode | | | U/f control |
| Frequency resolution (setpoint value) | Δf | Hz | 0.01 |
| Rated operational current | | | |
| At 150% overload | I _e | Α | 25 |
| At 110% overload | l _e | A | 32 |
| Note | .6 | | Rated operational current for a switching frequency of 1 - 16 kHz and an ambient temperature of +50 °C for a 150% overload and +40 °C for a 110% overload |
| Motor current limit | I | Α | 0.1 - 2 x I _H (CT) |
| | | | |

| Power loss | | | |
|---|------------------|-------------------|---|
| Heat dissipation at rated operational current I_e =150 % | P_{V} | W | 237.4 |
| Heat dissipation at rated operational current $I_{\rm B}$ =110% | P _V | W | 332.3 |
| Heat dissipation at current/speed [%] | ·V | VV | 502.0 |
| Current = 100% | | | |
| Speed = 0 % | P_V | W | 227.6 |
| <u> </u> | | W | 125.1 |
| Speed = 50 % | P _V | | |
| Speed = 90 % | P_V | W | 333.1 |
| Current = 50 % | D | 14/ | 0007 |
| Speed = 0 % | P _V | W | 290.7 |
| Speed = 50 % | P_V | W | 148.6 |
| Speed = 90 % | P_V | W | 169.6 |
| Current = 50 % | | | |
| Speed = 0 % | P_V | W | 90 |
| Speed = 50 % | P_V | W | 109.6 |
| Fan | | | temperature controlled |
| Internal fan delivery rate | | m ³ /h | 72 |
| Fitted with | | | Brake chopper |
| Frame size | | | FS3 |
| Motor feeder | | | |
| Note | | | for normal internally and externally ventilated 4 pole, three-phase asynchronous motors with 1500 $\rm rpm^{-1}$ at 50 Hz or 1800 $\rm min^{-1}$ at 60 Hz for PM motors |
| Note | | | Overload cycle for 60 s every 600 s |
| Note | | | at 230 V, 50 Hz |
| 150 % Overload | P | kW | 5.5 |
| 110 % Overload | P | kW | 7.5 |
| Note | | | at 230 V, 60 Hz |
| 150 % Overload | P | HP | 7.5 |
| 110 % Overload | P | HP | 10 |
| Braking function | | | |
| Standard braking torque | | | max. 30 % M _N |
| DC braking torque | | | adjustable to 150 % |
| Braking torque with external braking resistance | | | Max. 100% of rated operational current $I_{\rm e}$ with external braking resistor |
| minimum external braking resistance | R _{min} | Ω | 12 |
| DC braking | % | I/I _e | ≦ 150, adjustable |
| Control section | | | |
| External control voltage | U _c | V | 24 V DC (max. 100 mA options incl.) |
| Reference voltage | U _s | V | 10 V DC (max. 10 mA) |
| Analog inputs | | | 1, can be parameterized, 0–10 V DC, 2–10 V DC, 0/4–20 mA |
| Analog outputs | | | 1, parameterizable, 0 - 10 V |
| Digital inputs | | | 4, parameterizable, max. 30 V DC |
| Relay outputs | | | 1, parametrierbar, 1 Wechsler, 3 A (240 V AC) / 3 A (24 V DC) |
| Interface/field bus (built-in) | | | Modbus RTU |
| Expansion slots Assigned switching and protective elements Power Wiring | | | 1 |
| Safety device (fuse or miniature circuit-breaker) | | | |
| IEC (Type B, gG), 150 % | | | PKZM0-25 |
| IEC (Type B, gG), 110 % | | | PKZM0-32 |
| UL (Class CC or J) | | Α | 40 |
| Mains contactor | | | |
| 150 % overload (CT/I _H , at 50 °C) | | | DILM17-10 (230V50HZ,240V60HZ) |
| 110 % overload (VT/I _L , at 40 °C) | | | DILM17-10 (230V50HZ,240V60HZ) |
| Main choke | | | |

| 150 % overload (CT/I _H , at 50 °C) 110 % overload (VT/I _L , at 40 °C) Radio interference suppression filter (external, 150 %) Radio interference suppression filter (external, 110 %) Radio interference suppression filter, low leakage currents (external, 150 %) Radio interference suppression filter, low leakage currents (external, 150 %) Radio interference suppression filter, low leakage currents (external, 110 %) Note regarding radio interference suppression filter Optional external radio interference suppression filter for longer motor cable lengths and for use in different EMC environments DC link connection Braking resistance 10 % duty factor (DF) DX-BR022-1K4 |
|---|
| Radio interference suppression filter (external, 150 %) Radio interference suppression filter (external, 110 %) Radio interference suppression filter, low leakage currents (external, 150 %) Radio interference suppression filter, low leakage currents (external, 150 %) DX-EMC34-030-L DX-EMC34-030-L DX-EMC34-042-L Optional external radio interference suppression filter for longer motor cable lengths and for use in different EMC environments DC link connection Braking resistance |
| Radio interference suppression filter (external, 110 %) Radio interference suppression filter, low leakage currents (external, 150 %) Radio interference suppression filter, low leakage currents (external, 110 %) DX-EMC34-042-L Optional external radio interference suppression filter for longer motor cable lengths and for use in different EMC environments DC link connection Braking resistance |
| Radio interference suppression filter, low leakage currents (external, 150 %) Radio interference suppression filter, low leakage currents (external, 110 %) DX-EMC34-030-L DX-EMC34-042-L Optional external radio interference suppression filter for longer motor cable lengths and for use in different EMC environments DC link connection Braking resistance |
| Radio interference suppression filter, low leakage currents (external, 110 %) Note regarding radio interference suppression filter Optional external radio interference suppression filter lengths and for use in different EMC environments DC link connection Braking resistance |
| Note regarding radio interference suppression filter Optional external radio interference suppression filter for longer motor cable lengths and for use in different EMC environments DC link connection Braking resistance |
| DC link connection Braking resistance |
| Braking resistance |
| |
| 10 % duty factor (DF) DX-BR022-1K4 |
| |
| 20 % duty factor (DF) DX-BR012-3K1 |
| 40 % duty factor (DF) DX-BR012-5K1 |
| Notes concerning braking resistances: The brake resistors are assigned based on the maximum rated power of the variable frequency drive. Additional brake resistors and designs (e.g. differe cycles) are available upon request. |
| Motor feeder Company of the Company |
| motor choke |
| 150 % overload (CT/I _H , at 50 °C) DX-LM3-035 |
| 110 % overload (VT/I _L , at 40 °C) DX-LM3-035 |
| Sine filter |
| 150 % overload (CT/I _H , at 50 °C) DX-SIN3-032 |
| 110 % overload (VT/I _L , at 40 °C) DX-SIN3-032 |
| All-pole sine filter |
| 150 % overload (CT/I _H , at 50 °C) DX-SIN3-046-A |
| 110 % overload (VT/I _L , at 40 °C) DX-SIN3-046-A |

Design verification as per IEC/EN 61439

| Technical data for design verification | | | |
|---|-----------|----|--|
| Rated operational current for specified heat dissipation | In | Α | 32 |
| Equipment heat dissipation, current-dependent | P_{vid} | W | 332.3 |
| Operating ambient temperature min. | | °C | -10 |
| Operating ambient temperature max. | | °C | 50 |
| EC/EN 61439 design verification | | | |
| 10.2 Strength of materials and parts | | | |
| 10.2.2 Corrosion resistance | | | Meets the product standard's requirements. |
| 10.2.3.1 Verification of thermal stability of enclosures | | | Meets the product standard's requirements. |
| 10.2.3.2 Verification of resistance of insulating materials to normal heat | | | Meets the product standard's requirements. |
| 10.2.3.3 Verification of resistance of insulating materials to abnormal heat and fire due to internal electric effects $$ | | | Meets the product standard's requirements. |
| 10.2.4 Resistance to ultra-violet (UV) radiation | | | Meets the product standard's requirements. |
| 10.2.5 Lifting | | | Does not apply, since the entire switchgear needs to be evaluated. |
| 10.2.6 Mechanical impact | | | Does not apply, since the entire switchgear needs to be evaluated. |
| 10.2.7 Inscriptions | | | Meets the product standard's requirements. |
| 10.3 Degree of protection of ASSEMBLIES | | | Does not apply, since the entire switchgear needs to be evaluated. |
| 10.4 Clearances and creepage distances | | | Meets the product standard's requirements. |
| 10.5 Protection against electric shock | | | Does not apply, since the entire switchgear needs to be evaluated. |
| 10.6 Incorporation of switching devices and components | | | Does not apply, since the entire switchgear needs to be evaluated. |
| 10.7 Internal electrical circuits and connections | | | Is the panel builder's responsibility. |
| 10.8 Connections for external conductors | | | Is the panel builder's responsibility. |
| 10.9 Insulation properties | | | |
| 10.9.2 Power-frequency electric strength | | | Is the panel builder's responsibility. |
| 10.9.3 Impulse withstand voltage | | | Is the panel builder's responsibility. |
| 10.9.4 Testing of enclosures made of insulating material | | | Is the panel builder's responsibility. |
| 10.10 Temperature rise | | | The panel builder is responsible for the temperature rise calculation. Eaton will provide heat dissipation data for the devices. |

| 10.11 Short-circuit rating | Is the panel builder's responsibility. The specifications for the switchgear must be observed. |
|-------------------------------------|--|
| 10.12 Electromagnetic compatibility | Is the panel builder's responsibility. The specifications for the switchgear must be observed. |
| 10.13 Mechanical function | The device meets the requirements, provided the information in the instruction leaflet (IL) is observed. |

Technical data ETIM 8.0

| ecililical uata ETTIVI 0.0 | | |
|---|----|--|
| ow-voltage industrial components (EG000017) / Frequency converter =< 1 kV | | |
| lectric engineering, automation, process control engineering / Electrical drivi | | r / Static frequency converter = < 1 kV (ecl@ss10.0.1-27-02-31-01 [AKE177014]) |
| Aains voltage | V | 200 - 240 |
| Nains frequency | | 50/60 Hz |
| lumber of phases input | | 3 |
| lumber of phases output | | 3 |
| lax. output frequency | Hz | 400 |
| lax. output voltage | V | 240 |
| ominal output current I2N | А | 25.3 |
| lax. output at quadratic load at rated output voltage | kW | 7.5 |
| lax. output at linear load at rated output voltage | kW | 5.5 |
| elative symmetric net frequency tolerance | % | 10 |
| elative symmetric net voltage tolerance | % | 10 |
| umber of analogue outputs | | 1 |
| umber of analogue inputs | | 1 |
| lumber of digital outputs | | 0 |
| lumber of digital inputs | | 4 |
| /ith control element | | No |
| pplication in industrial area permitted | | Yes |
| pplication in domestic- and commercial area permitted | | Yes |
| upporting protocol for TCP/IP | | No |
| upporting protocol for PROFIBUS | | No |
| upporting protocol for CAN | | No |
| upporting protocol for INTERBUS | | No |
| upporting protocol for ASI | | No |
| upporting protocol for KNX | | No |
| upporting protocol for Modbus | | Yes |
| upporting protocol for Data-Highway | | No |
| upporting protocol for DeviceNet | | No |
| upporting protocol for SUCONET | | No |
| upporting protocol for LON | | No |
| upporting protocol for PROFINET IO | | No |
| upporting protocol for PROFINET CBA | | No |
| upporting protocol for SERCOS | | No |
| upporting protocol for Foundation Fieldbus | | No |
| upporting protocol for EtherNet/IP | | No |
| upporting protocol for AS-Interface Safety at Work | | No |
| upporting protocol for DeviceNet Safety | | No |
| upporting protocol for INTERBUS-Safety | | No |
| upporting protocol for PROFIsafe | | No |
| upporting protocol for SafetyBUS p | | No |
| upporting protocol for BACnet | | No |
| upporting protocol for other bus systems | | No |
| umber of HW-interfaces industrial Ethernet | | 0 |
| umber of interfaces PROFINET | | 0 |
| umber of HW-interfaces RS-232 | | 0 |
| Jumber of HW-interfaces RS-422 | | 0 |
| lumber of HW-interfaces RS-485 | | 1 |

| Number of HW-interfaces serial TTY | | | 0 |
|------------------------------------|---|----|-------------|
| Number of HW-interfaces USB | | | 0 |
| Number of HW-interfaces parallel | | | 0 |
| Number of HW-interfaces other | | | 0 |
| With optical interface | | | No |
| With PC connection | | | Yes |
| Integrated breaking resistance | | | Yes |
| 4-quadrant operation possible | | | Yes |
| Type of converter | | | U converter |
| Degree of protection (IP) | | | IP20 |
| Degree of protection (NEMA) | | | Other |
| Height | 1 | mm | 260 |
| Width | 1 | mm | 130 |
| Depth | | mm | 180 |

Approvals

| Product Standards | UL508C, CSA-C22.2 No. 274-13; IEC/EN61800-3; IEC/EN61800-5; CE marking |
|-----------------------------|--|
| UL File No. | E134360 |
| UL Category Control No. | NMMS, NMMS7 |
| CSA File No. | UL report applies to both US and Canada |
| North America Certification | UL listed, certified by UL for use in Canada |
| Suitable for | Branch circuits |
| Max. Voltage Rating | 3~240 V AC IEC: TN-S UL/CSA: 'Y' (Solidly Grounded Wey) |
| Degree of Protection | IP20/NEMA0 |

Dimensions





