



**Variable frequency drive, 500 V AC, 3-phase, 4.1 A, 2.2 kW, IP20/NEMA 0, 7-digital display assembly**



**Part no. DA1-354D1NB-A20C**  
**Catalog No. 177036**  
**Alternate Catalog No. DA1-354D1NB-A20C**  
**EL-Nummer 4110152**  
**(Norway)**

**Delivery program**

|                                    |                 |    |   |
|------------------------------------|-----------------|----|---|
| Product range                      |                 |    | Variable frequency drives   |
| Part group reference (e.g. DIL)    |                 |    | DA1   |
| Rated operational voltage          | U <sub>e</sub>  |    | 500 V AC, 3-phase<br>600 V AC, 3-phase  |
| Output voltage with V <sub>e</sub> | U <sub>2</sub>  |    | 500 V AC, 3-phase<br>600 V AC, 3-phase  |
| Mains voltage (50/60Hz)            | U <sub>LN</sub> | V  | 500 (-10%) - 600 (+10%)   |
| <b>Rated operational current</b>   |                 |    |   |
| At 150% overload                   | I <sub>e</sub>  | A  | 4.1   |
| Note                               |                 |    | Rated operational current at a switching frequency of 8 kHz and an ambient air temperature of +50 °C  |
| <b>Assigned motor rating</b>       |                 |    |   |
| Note                               |                 |    | for normal internally and externally ventilated 4 pole, three-phase asynchronous motors with 1500 rpm <sup>-1</sup> at 50 Hz or 1800 min <sup>-1</sup> at 60 Hz |
| Note                               |                 |    | Overload cycle for 60 s every 600 s   |
| Note                               |                 |    | at 500 V, 50 Hz   |
| 150 % Overload                     | P               | kW | 2.2   |
| 150 % Overload                     | I <sub>M</sub>  | A  | 4   |
| Note                               |                 |    | at 525 V, 50 Hz   |
| 150 % Overload                     | P               | kW | 2.2   |
| 150 % Overload                     | I <sub>M</sub>  | A  | 3.8   |
| Note                               |                 |    | at 550 - 600 V, 60 Hz   |
| 150 % Overload                     | P               | HP | 3   |
| 150 % Overload                     | I <sub>M</sub>  | A  | 3.9   |
| Degree of Protection               |                 |    | IP20/NEMA 0   |
| Interface/field bus (built-in)     |                 |    | OP-Bus (RS485)/Modbus RTU, CANopen®   |
| Fieldbus connection (optional)     |                 |    | Ethernet IP<br>DeviceNet<br>PROFIBUS<br>PROFINET<br>Modbus-TCP<br>EtherCAT<br>SmartWire-DT  |
| Fitted with                        |                 |    | Brake chopper<br>7-digital display assembly<br>Additional PCB protection  |
| Frame size                         |                 |    | FS2   |
| Connection to SmartWire-DT         |                 |    | yes<br>in conjunction with DX-NET-SWD1 SmartWire DT module  |

**Technical data**

|                     |                |   |   |
|---------------------|----------------|---|---|
| <b>General</b>      |                |   |   |
| Standards           |                |   | Specification for general requirements: IEC/EN 61800-2<br>EMC requirements: IEC/EN 61800-3<br>Safety requirements: IEC/EN 61800-5-1 |
| Certifications      |                |   | CE, UL, cUL, RCM, UkrSEPRO, EAC   |
| Production quality  |                |   | RoHS, ISO 9001  |
| Climatic proofing   | ρ <sub>w</sub> | % | < 95%, average relative humidity (RH), non-condensing, non-corrosive  |
| Air quality         |                |   | 3C2, 3S2  |
| Ambient temperature |                |   |   |

|   |            |     |   |
|---|------------|-----|---|
| Operating ambient temperature min.                          |            | °C  | -10   |
| Operating ambient temperature max.                          |            | °C  | +50   |
|   |            |     | operation (with 150 % overload)   |
| Storage   | θ          | °C  | -40 - +60   |
| Mounting position   |            |     | Vertical  |
| Altitude  |            | m   | 0 - 1000 m above sea level<br>Above 1000 m: 1% derating for every 100 m<br>max. 4000 m  |
| Degree of Protection  |            |     | IP20/NEMA 0   |
| Protection against direct contact                           |            |     | BGV A3 (VBG4, finger- and back-of-hand proof)   |
| <b>Main circuit</b>   |            |     |   |
| <b>Supply</b>   |            |     |   |
| Rated operational voltage                                   | $U_e$      |     | 500 V AC, 3-phase<br>600 V AC, 3-phase  |
| Mains voltage (50/60Hz)                                     | $U_{LN}$   | V   | 500 (-10%) - 600 (+10%)   |
| Input current (150% overload)                               | $I_{LN}$   | A   | 4.9   |
| System configuration  |            |     | AC supply systems with earthed center point   |
| Supply frequency  | $f_{LN}$   | Hz  | 50/60   |
| Frequency range   | $f_{LN}$   | Hz  | 48 - 62   |
| Mains switch-on frequency                                   |            |     | Maximum of one time every 30 seconds  |
| <b>Power section</b>  |            |     |   |
| Function  |            |     | Variable frequency drive with internal DC link and IGBT inverter  |
| Overload current (150% overload)                            | $I_L$      | A   | 7.35  |
| max. starting current (High Overload)                       | $I_H$      | %   | 200   |
| Note about max. starting current                            |            |     | for 4 seconds every 40 seconds  |
| Output voltage with $V_e$                                   | $U_2$      |     | 500 V AC, 3-phase<br>600 V AC, 3-phase  |
| Output Frequency  | $f_2$      | Hz  | 0 - 50/60 (max. 500)  |
| Switching frequency   | $f_{PWM}$  | kHz | 8<br>adjustable 4 - 24 (audible)  |
| Operation Mode  |            |     | U/f control<br>Speed control with slip compensation<br>sensorless vector control (SLV)<br>optional: Vector control with feedback (CLV)                            |
| Frequency resolution (setpoint value)                       | $\Delta f$ | Hz  | 0.1   |
| Rated operational current                                   |            |     |   |
| At 150% overload  | $I_e$      | A   | 4.1   |
| Note  |            |     | Rated operational current at a switching frequency of 8 kHz and an ambient air temperature of +50 °C  |
| Power loss  |            |     |   |
| Heat dissipation at rated operational current $I_e = 150\%$ | $P_V$      | W   | 66  |
| Efficiency  | $\eta$     | %   | 97  |
| Maximum leakage current to ground (PE) without motor        | $I_{PE}$   | mA  | 4.1   |
| Fitted with   |            |     | Brake chopper<br>7-digital display assembly<br>Additional PCB protection  |
| Safety function   |            |     | STO (Safe Torque Off, SIL2, PLd Cat 3)  |
| Frame size  |            |     | FS2   |
| <b>Motor feeder</b>   |            |     |   |
| Note  |            |     | for normal internally and externally ventilated 4 pole, three-phase asynchronous motors with $1500 \text{ rpm}^{-1}$ at 50 Hz or $1800 \text{ min}^{-1}$ at 60 Hz |
| Note  |            |     | Overload cycle for 60 s every 600 s   |
| Note  |            |     | at 500 V, 50 Hz   |
| 150 % Overload  | P          | kW  | 2.2   |
| Note  |            |     | at 525 V, 50 Hz   |
| 150 % Overload  | P          | kW  | 2.2   |
| Note  |            |     | at 550 - 600 V, 60 Hz   |
| 150 % Overload  | P          | HP  | 3   |
| maximum permissible cable length                            | l          | m   | screened: 100<br>screened, with motor choke: 200  |

|   |           |          |   |
|---|-----------|----------|---|
|   |           |          | unscreened: 150<br>unscreened, with motor choke: 300                        |
| Apparent power                                  |           |          |   |
| Apparent power at rated operation 600 V         | S         | kVA      | 4.26  |
| Braking function                                |           |          |   |
| Standard braking torque                         |           |          | max. 30 % $M_N$   |
| DC braking torque                               |           |          | max. 100% of rated operational current $I_e$ , variable                     |
| Braking torque with external braking resistance |           |          | Max. 100% of rated operational current $I_e$ with external braking resistor |
| minimum external braking resistance             | $R_{min}$ | $\Omega$ | 50  |
| Switch-on threshold for the braking transistor  | $U_{DC}$  | V        | 975 V DC  |

### Control section

|                                |       |   |  |
|--------------------------------|-------|---|--|
| External control voltage       | $U_c$ | V | 24 V DC (max. 100 mA)  |
| Reference voltage              | $U_s$ | V | 10 V DC (max. 10 mA)   |
| Analog inputs                  |       |   | 2, parameterizable, 0 - 10 V DC, 0/4 - 20 mA   |
| Analog outputs                 |       |   | 2, parameterizable, 0 - 10 V, 0/4 - 20 mA  |
| Digital inputs                 |       |   | 3, parameterizable, max. 30 VDC, max. 5 for non-parameterized analog inputs              |
| Digital outputs                |       |   | 2, parameterizable, 24 V DC  |
| Relay outputs                  |       |   | 2, parameterizable, 1 N/O and 1 changeover contact, 6 A (250 V, AC-1) / 5 A (30 V, DC-1) |
| Interface/field bus (built-in) |       |   | OP-Bus (RS485)/Modbus RTU, CANopen®  |

### Assigned switching and protective elements

|   |  |   |  |
|---|--|---|--|
| Power Wiring                                      |  |   |  |
| Safety device (fuse or miniature circuit-breaker) |  |   |  |
| IEC (Type B, gG), 150 %                           |  |   | 10NHG000B                                      |
| Notes   |  |   | NH fuse used together with TB00-D fuse base    |
| UL (Class CC or J)                                |  | A | 10   |
| Notes   |  |   | LPJ fuse used together with J60060-3 fuse base |
| UL (Class CC or J)                                |  | A | LPJ-10SP                                       |
| Mains contactor                                   |  |   |  |
| 150 % overload (CT/I <sub>H</sub> , at 50 °C)     |  |   | DILM7  |
| Main choke  |  |   |  |
| 150 % overload (CT/I <sub>H</sub> , at 50 °C)     |  |   | DX-LN3-006                                     |
| DC link connection                                |  |   |  |
| Braking resistance                                |  |   |  |
| 10 % duty factor (DF)                             |  |   | DX-BR200-0K4                                   |
| 20 % duty factor (DF)                             |  |   | DX-BR200-0K8                                   |
| Motor feeder                                      |  |   |  |
| motor choke                                       |  |   |  |
| 150 % overload (CT/I <sub>H</sub> , at 50 °C)     |  |   | DX-LM3-005                                     |
| Sine filter                                       |  |   |  |
| 150 % overload (CT/I <sub>H</sub> , at 50 °C)     |  |   | SIN-0005-6-0-P                                 |

### Design verification as per IEC/EN 61439

|  |            |    |  |
|--|------------|----|--|
| Technical data for design verification                   |            |    |  |
| Rated operational current for specified heat dissipation | $I_n$      | A  | 4.1  |
| Heat dissipation per pole, current-dependent             | $P_{vid}$  | W  | 0  |
| Equipment heat dissipation, current-dependent            | $P_{vid}$  | W  | 66   |
| Static heat dissipation, non-current-dependent           | $P_{vs}$   | W  | 0  |
| Heat dissipation capacity                                | $P_{diss}$ | W  | 0  |
| Operating ambient temperature min.                       |            | °C | -10  |
| Operating ambient temperature max.                       |            | °C | 50   |
|  |            |    | Operation (with 150 % overload)            |
| IEC/EN 61439 design verification                         |            |    |  |
| 10.2 Strength of materials and parts                     |            |    |  |
| 10.2.2 Corrosion resistance                              |            |    | Meets the product standard's requirements. |

|  |  |  |
|--|--|--|
| 10.2.3.1 Verification of thermal stability of enclosures   |  | Meets the product standard's requirements.   |
| 10.2.3.2 Verification of resistance of insulating materials to normal heat   |  | Meets the product standard's requirements.   |
| 10.2.3.3 Verification of resistance of insulating materials to abnormal heat and fire due to internal electric effects |  | Meets the product standard's requirements.   |
| 10.2.4 Resistance to ultra-violet (UV) radiation   |  | Meets the product standard's requirements.   |
| 10.2.5 Lifting   |  | Does not apply, since the entire switchgear needs to be evaluated.   |
| 10.2.6 Mechanical impact   |  | Does not apply, since the entire switchgear needs to be evaluated.   |
| 10.2.7 Inscriptions  |  | Meets the product standard's requirements.   |
| 10.3 Degree of protection of ASSEMBLIES  |  | Does not apply, since the entire switchgear needs to be evaluated.   |
| 10.4 Clearances and creepage distances   |  | Meets the product standard's requirements.   |
| 10.5 Protection against electric shock   |  | Does not apply, since the entire switchgear needs to be evaluated.   |
| 10.6 Incorporation of switching devices and components   |  | Does not apply, since the entire switchgear needs to be evaluated.   |
| 10.7 Internal electrical circuits and connections  |  | Is the panel builder's responsibility.   |
| 10.8 Connections for external conductors   |  | Is the panel builder's responsibility.   |
| 10.9 Insulation properties   |  |  |
| 10.9.2 Power-frequency electric strength   |  | Is the panel builder's responsibility.   |
| 10.9.3 Impulse withstand voltage   |  | Is the panel builder's responsibility.   |
| 10.9.4 Testing of enclosures made of insulating material   |  | Is the panel builder's responsibility.   |
| 10.10 Temperature rise   |  | The panel builder is responsible for the temperature rise calculation. Eaton will provide heat dissipation data for the devices. |
| 10.11 Short-circuit rating   |  | Is the panel builder's responsibility. The specifications for the switchgear must be observed.                                   |
| 10.12 Electromagnetic compatibility  |  | Is the panel builder's responsibility. The specifications for the switchgear must be observed.                                   |
| 10.13 Mechanical function  |  | The device meets the requirements, provided the information in the instruction leaflet (IL) is observed.                         |

## Technical data ETIM 7.0

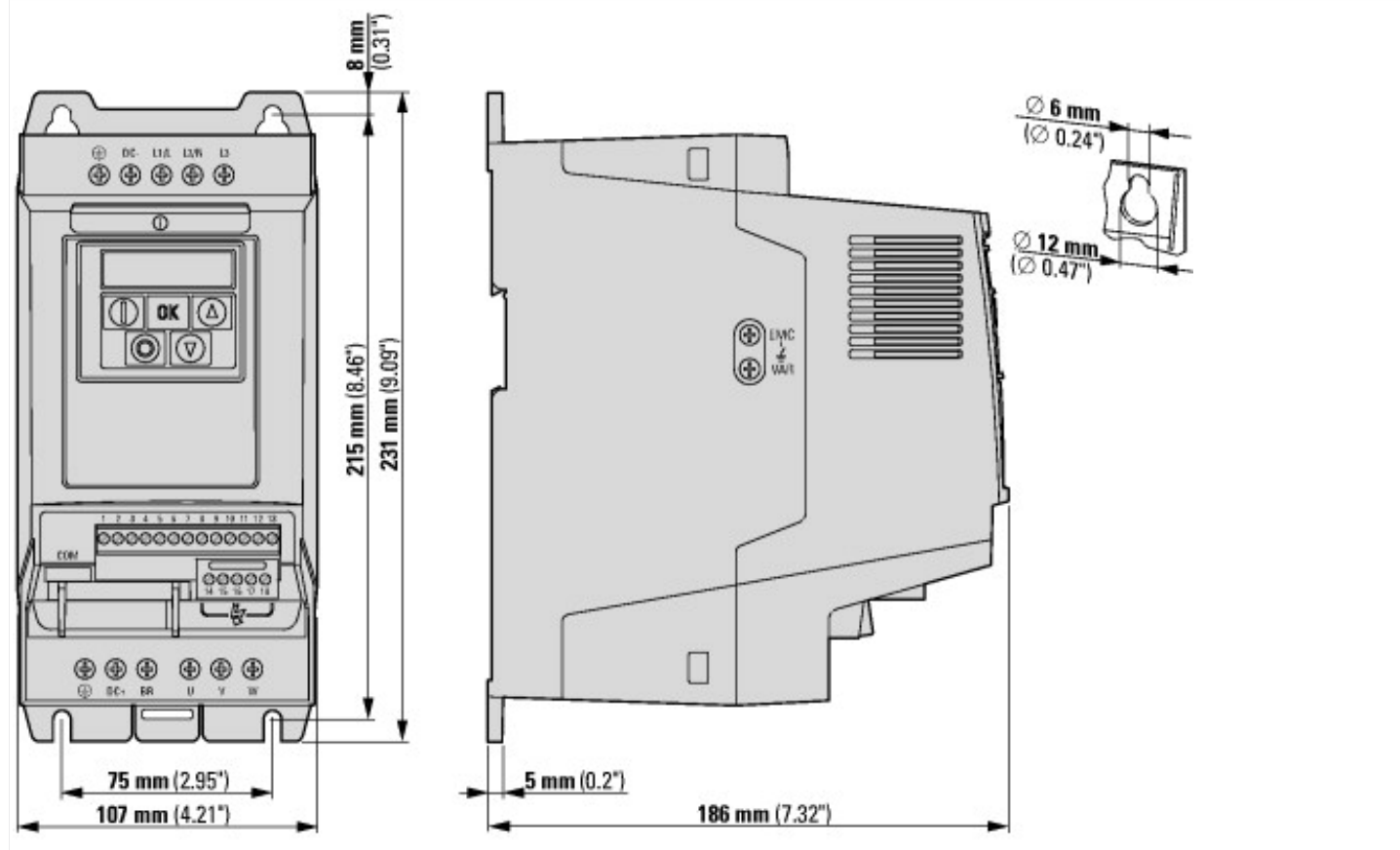
|  |    |           |
|--|----|-----------|
| Low-voltage industrial components (EG000017) / Frequency converter <= 1 kV (EC001857)  |    |           |
| Electric engineering, automation, process control engineering / Electrical drive / Static frequency converter / Static frequency converter = < 1 kV (ecl@ss10.0.1-27-02-31-01 [AKE177014]) |    |           |
| Mains voltage  | V  | 500 - 600 |
| Mains frequency  |    | 50/60 Hz  |
| Number of phases input   |    | 3         |
| Number of phases output  |    | 3         |
| Max. output frequency  | Hz | 500       |
| Max. output voltage  | V  | 600       |
| Nominal output current I2N   | A  | 4.1       |
| Max. output at quadratic load at rated output voltage  | kW | 2.2       |
| Max. output at linear load at rated output voltage   | kW | 2.2       |
| Relative symmetric net frequency tolerance   | %  | 10        |
| Relative symmetric net voltage tolerance   | %  | 10        |
| Number of analogue outputs   |    | 2         |
| Number of analogue inputs  |    | 2         |
| Number of digital outputs  |    | 2         |
| Number of digital inputs   |    | 5         |
| With control unit  |    | Yes       |
| Application in industrial area permitted   |    | Yes       |
| Application in domestic- and commercial area permitted   |    | No        |
| Supporting protocol for TCP/IP   |    | No        |
| Supporting protocol for PROFIBUS   |    | Yes       |
| Supporting protocol for CAN  |    | Yes       |
| Supporting protocol for INTERBUS   |    | No        |
| Supporting protocol for ASI  |    | No        |
| Supporting protocol for KNX  |    | No        |
| Supporting protocol for MODBUS   |    | Yes       |
| Supporting protocol for Data-Highway   |    | No        |
| Supporting protocol for DeviceNet  |    | Yes       |

|   |  |    |             |
|---|--|----|-------------|
| Supporting protocol for SUCONET                     |  |    | No          |
| Supporting protocol for LON                         |  |    | No          |
| Supporting protocol for PROFINET IO                 |  |    | Yes         |
| Supporting protocol for PROFINET CBA                |  |    | No          |
| Supporting protocol for SERCOS                      |  |    | No          |
| Supporting protocol for Foundation Fieldbus         |  |    | No          |
| Supporting protocol for EtherNet/IP                 |  |    | Yes         |
| Supporting protocol for AS-Interface Safety at Work |  |    | No          |
| Supporting protocol for DeviceNet Safety            |  |    | No          |
| Supporting protocol for INTERBUS-Safety             |  |    | No          |
| Supporting protocol for PROFIsafe                   |  |    | No          |
| Supporting protocol for SafetyBUS p                 |  |    | No          |
| Supporting protocol for BACnet                      |  |    | No          |
| Supporting protocol for other bus systems           |  |    | Yes         |
| Number of HW-interfaces industrial Ethernet         |  |    | 0           |
| Number of interfaces PROFINET                       |  |    | 0           |
| Number of HW-interfaces RS-232                      |  |    | 0           |
| Number of HW-interfaces RS-422                      |  |    | 0           |
| Number of HW-interfaces RS-485                      |  |    | 1           |
| Number of HW-interfaces serial TTY                  |  |    | 0           |
| Number of HW-interfaces USB                         |  |    | 0           |
| Number of HW-interfaces parallel                    |  |    | 0           |
| Number of HW-interfaces other                       |  |    | 0           |
| With optical interface                              |  |    | No          |
| With PC connection                                  |  |    | Yes         |
| Integrated breaking resistance                      |  |    | Yes         |
| 4-quadrant operation possible                       |  |    | No          |
| Type of converter                                   |  |    | U converter |
| Degree of protection (IP)                           |  |    | IP20        |
| Degree of protection (NEMA)                         |  |    | Other       |
| Height  |  | mm | 231         |
| Width   |  | mm | 107         |
| Depth   |  | mm | 186         |

## Approvals

|                                      |  |  |   |
|--------------------------------------|--|--|---|
| Product Standards                    |  |  | UL 508C; CSA-C22.2 No. 14; IEC/EN61800-3; IEC/EN61800-5; CE marking |
| UL File No.                          |  |  | E172143   |
| UL Category Control No.              |  |  | NMMS, NMMS7   |
| CSA File No.                         |  |  | UL report applies to both US and Canada                             |
| North America Certification          |  |  | UL listed, certified by UL for use in Canada                        |
| Specially designed for North America |  |  | No  |
| Suitable for                         |  |  | Branch circuits   |
| Max. Voltage Rating                  |  |  | 3~ 600 V AC (+10 %) IEC: TN-S UL/CSA: "Y" (Solidly Grounded Wey)    |
| Degree of Protection                 |  |  | IEC: IP20   |

## Dimensions



## Assets (links)

### Declaration of CE Conformity

00003239

### Instruction Leaflets

IL04020010Z2018\_04

### Manuals

MN04020005Z\_EN (English)

MN04020006Z\_EN (English)

## Additional product information (links)

### IL04020010Z DA1 variable frequency drives (FS2 - FS3, IP20)

IL04020010Z DA1 variable frequency drives (FS2 ftp://ftp.moeller.net/DOCUMENTATION/AWA\_INSTRUCTIONS/IL04020010Z2018\_04.pdf - FS3, IP20)

### MN04020005Z DA1 variable frequency drives, Installation manual

MN04020005Z Frequenzumrichter DA1, Installationshandbuch - Deutsch ftp://ftp.moeller.net/DOCUMENTATION/AWB\_MANUALS/MN04020005Z\_DE.pdf

MN04020005Z DA1 variable frequency drives, Installation manual - English ftp://ftp.moeller.net/DOCUMENTATION/AWB\_MANUALS/MN04020005Z\_EN.pdf

MN04020005Z Convertitore di frequenza DA1, manuale Installazione - italiano ftp://ftp.moeller.net/DOCUMENTATION/AWB\_MANUALS/MN04020005Z\_IT.pdf

### MN04020006Z DA1 variable frequency drives, Parameters manual

MN04020006Z Frequenzumrichter DA1, Parameterhandbuch - Deutsch ftp://ftp.moeller.net/DOCUMENTATION/AWB\_MANUALS/MN04020006Z\_DE.pdf

MN04020006Z DA1 variable frequency drives, Parameters manual - English ftp://ftp.moeller.net/DOCUMENTATION/AWB\_MANUALS/MN04020006Z\_EN.pdf

MN04020006Z Convertitore di frequenza DA1, manuale Parametri - italiano ftp://ftp.moeller.net/DOCUMENTATION/AWB\_MANUALS/MN04020006Z\_IT.pdf

CA04020001Z-EN Product Range Catalog: Efficient Engineering for Starting and Controlling Motors http://www.eaton.eu/DE/ecm/groups/public/@pub/@europe/@electrical/documents/content/pct\_1095238.pdf