

Variable Frequency Drive, $3\sim/3\sim400$ V, 39 A, 18.5 kW, Vector control, EMC-Filter, Brake-Chopper

Powering Business Worldwide

Part no. DA1-34039FB-B55N Article no. 169325 Catalog No. DA1-34039FB-B55N

Delivery programme

Delivery programme			
Product range			Variable frequency drives
Rated operational voltage	U _e		400 V AC, 3-phase
Output voltage with V _e	U ₂		400 V AC, 3-phase
Mains voltage (50/60Hz)	U _{LN}	V	380 (-10%) - 480 (+10%)
Rated operational current			
At 150% overload	l _e	Α	39
Note			Rated operational current at an operating frequency of 4 kHz and an ambient air temperature of +40 $^{\circ}\text{C}$
Note			Overload cycle for 60 s every 600 s
Assigned motor rating			
Note			for normal internally and externally ventilated 4 pole, three-phase asynchronous motors with 1500 rpm ⁻¹ at 50 Hz or 1800 min ⁻¹ at 60 Hz
Note			Overload cycle for 60 s every 600 s
Note			at 400 V, 50 Hz
150 % Overload	Р	kW	18.5
150 % Overload	l _e	Α	36
Note			at 440 - 480 V, 60 Hz
150 % Overload	Р	HP	25
150 % Overload	l _e	Α	34
Degree of Protection			IP55/NEMA 12
Interface/field bus (built-in)			OP-Bus (RS485)/Modbus RTU, CANopen®
Fieldbus connection (optional)			Ethernet IP DeviceNet PROFIBUS PROFINET Modbus-TCP EtherCAT BACnet/IP SmartWire-DT
Fitted with			Radio interference suppression filter Brake chopper OLED display
Frame size			FS4
Connection to SmartWire-DT			with SmartWire-DT module DX-NET-SWD2

Technical data

General

Conoral			
Standards			Specification for general requirements: IEC/EN 61800-2 EMC requirements: IEC/EN 61800-3 Safety requirements: IEC/EN 61800-5-1
Certifications			CE, cUL, UL, c-Tick, Ukr Sepro, EAC
Production quality			RoHS, ISO 9001
Climatic proofing	ρ_{W}	%	< 95%, average relative humidity (RH), non-condensing, non-corrosive (EN 50178)
Ambient temperature		°C	
operation (150 % overload)	9	°C	-10 - +40
Storage	9	°C	-40 - +60
Radio interference level			

			C1, C2, C3, depending on the motor cable length, the connected load, and ambient conditions. External radio interference suppression filters (optional) may be necessary.
Environment (EMC)			1st and 2nd environments
maximum motor cable length	l	m	C1 ≤ 1 m C2 ≤ 5 m C3 ≤ 25 m
Mounting position Altitude		m	Vertical 0 - 1000 m above sea level above 1000 m with 1 % performance reduction per 100 m max. 4000 m
Degree of Protection			IP55/NEMA 12
Protection against direct contact			BGV A3 (VBG4, finger- and back-of-hand proof)
Main circuit			
Supply			
Rated operational voltage	U _e		400 V AC, 3-phase
Mains voltage (50/60Hz)	U _{LN}	V	380 (-10%) - 480 (+10%)
Input current (150% overload)	I _{LN}	Α	40
System configuration			AC supply systems with earthed center point
Supply frequency	f _{LN}	Hz	50/60
Frequency range	f _{LN}	Hz	48 - 62
Mains switch-on frequency	LIV		Maximum of one time every 30 seconds
Power section			Wideling of the time every to seconds
Function			Frequency inverter with internal DC link and IGBT inverter
Overload current (150% overload)	h	Α	58.5
	IL .		
max. starting current (High Overload)	I _H	%	200
Note about max. starting current			for 4 seconds
Output voltage with V _e	U ₂		400 V AC, 3-phase
Output Frequency	f ₂	Hz	0 - 50/60 (max. 500)
Switching frequency	f_{PWM}	kHz	8 adjustable 4 - 24 (audible)
Operation Mode			U/f control Speed control with slip compensation sensorless vector control (SLV) optional: Vector control with feedback (CLV)
Frequency resolution (setpoint value)	Δf	Hz	0.1
Rated operational current			
At 150% overload	l _e	Α	39
Note			Rated operational current at an operating frequency of 4 kHz and an ambient air temperature of +40 °C
Power loss			
Heat dissipation at rated operational current	P_{V}	W	444
Efficiency	η	%	97.6
Maximum leakage current to ground (PE) without motor	I _{PE}	mA	2.47
Fitted with			Radio interference suppression filter Brake chopper OLED display
Safety function			STO (Safe Torque Off)
Frame size			FS4
Motor feeder			
Note			for normal internally and externally ventilated 4 pole, three-phase asynchronous motors with 1500 rpm ⁻¹ at 50 Hz or 1800 min ⁻¹ at 60 Hz
Note			Overload cycle for 60 s every 600 s
Note			at 400 V, 50 Hz
150 % Overload	Р	kW	18.5
Note			at 440 - 480 V, 60 Hz
150 % Overload	Р	НР	25
maximum permissible cable length	I	m	screened: 100 screened, with motor choke: 200 unscreened: 150 unscreened, with motor choke: 300

Apparent power at rated operation 400 V S kVA 27.02 Apparent power at rated operation 480 V S kVA 24.2 Braking function Standard braking torque	Apparent power			
Apparent power at rated operation 480 V Braking function Standard braking torque DC braking torque Braking torque with external braking resistance minimum external braking resistance minimum external braking resistance minimum external braking resistance Mover braking torque with external braking resistance minimum external braking resistance Mover braking transistor Braking torque with external braking resistance Mover braking transistor Remin		S	kVΔ	27 02
Braking function Standard braking torque DC braking torque Braking torque with external braking resistance minimum external braking resistance Braking torque with external braking resistance minimum external braking resistance Remia Duc V V 700 V DC Control section External control voltage Us V V 24 V DC (max. 100 mA) Reference voltage Us V V 10 V DC (max. 100 mA) Analog inputs Analog outputs Digital inputs Analog outputs Digital inputs Reley outputs Digital inputs Di				
Standard braking torque DC braking torque Braking torque with external braking resistance minimum external braking resistance minimum external braking resistance minimum external braking resistance Remin 0 0 22 Switch-on threshold for the braking transistor Upc V 0 780 V DC CONTROL Section External control voltage Upc V 0 24 V DC (max. 10 mA) Analog ontputs Upc V 0 10 V DC (max. 10 mA) Analog ontputs Upc V 0 10 V DC (max. 10 mA) Upc V 0 10 V DC (max. 10 mA) Upc V 0 10 V DC (max. 10 mA) Upc V 0 10 V DC (max. 10 mA) Upc V 0 10 V DC (max. 10 mA) Upc V 0 10 V DC (max. 10 mA) Upc V 0 10 V DC (max. 10 mA) Upc V 0 10 V DC (max. 10 mA) Upc V 0 10 V DC (max. 10 mA) Upc V 0 10 V DC (max. 10 mA) Upc V 0 10 V DC (max. 10 mA) Upc V 0 10 V DC (max. 10 mA) Upc V 0 10 V DC (max. 10 mA) Upc V 0 10 V DC (max. 10 mA) Upc V 0 10 V DC (max. 10 mA) Upc V 0 10 V DC (max. 10 mA) Upc V 0 10 V DC (max. 10 mA) Upc V 0 10 V DC (max. 10 mA) Upc V 0 10 V DC (max. 10 mA) Upc V 0 10 V DC (max. 10 mA) Upc V 0 10 V DC (max. 10 mA) Upc V 0 10 V DC (max. 10 mA) Upc V 0 10 V DC (max. 10 mA) Upc V 0 10 V DC (max. 10 mA) Upc V 0 10 V DC (max. 10 mA) Upc V 0 10 V DC (max. 10 mA) Upc V 0 10 V DC (max. 10 mA) Upc V 0 10 V DC (max. 10 mA) Upc V 0 10 V DC (max. 10 mA) Upc V 0 10 V DC (max. 10 mA) Upc V 0 10 V DC (max. 10 mA) Upc V 0 10 V DC (max. 10 mA) Upc V 0 10 V DC (max. 10 mA) Upc V 0 10 V DC (max. 10 mA) Upc V 0 10 V DC (max. 10 mA) Upc V 0 10 V DC (max. 10 mA) Upc V 0 10 V DC (max. 10 mA) Upc V 0 10 V DC (max. 10 mA) Upc V 0 10 V DC (max. 10 mA) Upc V 0 10 V DC (max. 10 mA) Upc V 0 10 V DC (max. 10 mA) Upc V 0 10 V DC (max. 10 mA) Upc V 0 10 V DC (max. 10 mA) Upc V 0 10 V DC (max. 10 mA) Upc V 0 10 V DC (max. 10 mA) Upc V 0 10 V DC (max. 10 mA) Upc V 0 10 V DC (max. 10 mA) Upc V 0 10 V DC (max. 10 mA) Upc V 0 10 V DC (max. 10 mA) Upc V 0 10 V DC (max. 10 mA) Upc V 0 10 V DC (max. 10 mA) Upc V 0 10 V DC (max. 10 mA) Upc V 0 10 V DC (max. 10 mA) Upc V 0 10 V 0 V 0 V 0 V 0 V 0 V 0 V 0 V		3	KVA	32.42
DC braking torque with external braking resistance Braking torque with external braking resistance minimum external braking resistance minimum external braking resistance Remin	•			00.0/. NA
Braking torque with external braking resistance minimum external braking resistance minimum external braking resistance Rmin 0 2 2 8 witch-on threshold for the braking transistor Upc V 780 V DC Control section External control voltage External control voltage Nalog inputs Analog inputs Analog outputs Digital inputs Digital inputs Digital outputs External control voltage Relevance voltage Digital inputs Digital outputs Digital outputs External control voltage Relay outputs Digital outputs				"
minimum external braking resistance R _{min} 0 22 Switch-on threshold for the braking transistor U _{DC} V 780 V DC Control section V 24 V DC (max. 10 m A) External control voltage U _C V 24 V DC (max. 10 m A) Reference voltage U _S V 10 V DC (max. 10 m A) Analog inputs 2, parameterizable, 0 - 10 V DC, 0/4 - 20 m A Analog outputs 2, parameterizable, 0 - 10 V, 0/4 - 20 m A Digital outputs 3, parameterizable, max. 30 VDC, max. 5 for non-parameterized analog inputs Relay outputs 2, parameterizable, 24 V DC Relay outputs 2, parameterizable, 1 N/O and 1 changeover contact, 6 A (250 V, AC-1)/5 A (30 V, DC-1) Relay outputs 0P-Bus (RS485)/Modbus RTU, CANopen® Assigned switching and protective elements FAZ-B50/3 Power Wiring FAZ-B50/3 150 % overload (CT/I _H , at 50 °C) DX-LM3-050 Motor feeder DX-LM3-050 150 % overload (CT/I _H , at 50 °C) DX-LM3-050 150 % overload (CT/I _H , at 50 °C) DX-LM3-050 150 % overload (CT/I _H , at 50 °C) DX-LM3-050 <td>DC braking torque</td> <td></td> <td></td> <td>100 %, adjustable</td>	DC braking torque			100 %, adjustable
Switch-on threshold for the braking transistor V _{DC} V 780 V DC Control section V 24 V DC (max. 100 mA) External control voltage U _C V 24 V DC (max. 10 mA) Reference voltage U _S V 10 V DC (max. 10 mA) Analog inputs 2, parameterizable, 0 - 10 V DC, 0/4 - 20 mA Analog outputs 2, parameterizable, 0 - 10 V, 0/4 - 20 mA Digital outputs 3, parameterizable, max. 30 VDC, max. 5 for non-parameterized analog inputs Relay outputs 2, parameterizable, 24 V DC Relay outputs 2, parameterizable, 1 N/O and 1 changeover contact, 6 A (250 V, AC-1)/5 A (30 V, DC-1) Interface/field bus (built-in) 0P-Bus (RS485)/Modbus RTU, CANopen® Assigned switching and protective elements FAZ-B50/3 Power Wiring FAZ-B50/3 150 % overload (CT/I _H , at 50 °C) DX-LM3-050 Motor feeder DX-LM3-050 150 % overload (CT/I _H , at 50 °C) DX-LM3-050 150 % overload (CT/I _H , at 50 °C) DX-LM3-050 150 % overload (CT/I _H , at 50 °C) DX-LM3-050 150 % overload (CT/I _H , at 50 °C) DX-LM3-050 <th< td=""><td>Braking torque with external braking resistance</td><td></td><td></td><td>max. 100% rated operational current I_e, with external braking resistance</td></th<>	Braking torque with external braking resistance			max. 100% rated operational current I _e , with external braking resistance
Control section External control voltage Uc V 24 V DC (max. 100 mA) Reference voltage Us V 10 V DC (max. 10 mA) Analog inputs 2, parameterizable, 0 - 10 V DC, 0/4 - 20 mA Analog outputs 2, parameterizable, 0 - 10 V, 0/4 - 20 mA Digital inputs 3, parameterizable, 0 - 10 V, 0/4 - 20 mA Digital outputs 2, parameterizable, ana. 30 VDC, max. 5 for non-parameterized analog inputs Relay outputs 2, parameterizable, 2 V DC Interface/field bus (built-in) 2, parameterizable, 1 N/O and 1 changeover contact, 6 A (250 V, AC-1)/5 A (30 V, Co-1)/5 C (30 V, Co-1)/5 A (30 V,	minimum external braking resistance	R_{min}	Ω	22
External control voltage Reference voltage Analog inputs Analog inputs Analog outputs Analog outputs Analog outputs Digital inputs Digital outputs Relay outputs Relay outputs Relay outputs Relay outputs Assigned switching and protective elements Power Wiring IEC (Typ B, gG) 150% overload (CT/I _H , at 50 °C) Motor feeder 150% overload (CT/I _H , at 50 °C) 150% overload (CT/I _H , at	Switch-on threshold for the braking transistor	U_{DC}	V	780 V DC
Reference voltage Analog inputs Analog outputs Analog outputs Digital inputs Digital outputs Digital outputs Digital outputs Digital outputs Relay outputs Relay outputs Relay outputs Relay outputs Relay outputs Digital outputs Relay outputs Relay outputs Relay outputs Digital outputs Relay outputs Digital outputs Relay outputs Relay outputs Digital outputs Digital outputs Digital outputs Digital outputs Relay outputs Digital out	Control section			
Analog inputs Analog outputs Digital inputs Digital outputs Relay outputs Digital outputs Digi	External control voltage	U _c	V	24 V DC (max. 100 mA)
Analog outputs Digital inputs Digital outputs Digital outputs Relay outputs Relay outputs Interface/field bus (built-in) Assigned switching and protective elements Power Wirring IEC (Typ B, gG) 150 % overload (CT/I _H , at 50 °C) Motor feeder 150 % overload (CT/I _H , at 50 °C) 150 % overload (CT/I _H , at 50 °C) 150 % overload (CT/I _H , at 50 °C) 150 % duty factor (DF) A parameterizable, 0 - 10 V, 0/4 - 20 mA 2, parameterizable, 24 V DC 2, parameterizable, 1 N/O and 1 changeover contact, 6 A (250 V, AC-1) / 5 A (30 V, DC-1) 2, parameterizable, 24 V DC 2, parameterizable,	Reference voltage	U_s	V	10 V DC (max. 10 mA)
Digital inputs Digital outputs 2, parameterizable, pax 30 VDC, max 5 for non-parameterized analog inputs Relay outputs Cheerface/field bus (built-in) Cheer	Analog inputs			2, parameterizable, 0 - 10 V DC, 0/4 - 20 mA
Digital outputs Relay outputs 2, parameterizable, 24 V DC 2, parameterizable, 1 N/O and 1 changeover contact, 6 A (250 V, AC-1)/5 A (30 V, DC-1) Interface/field bus (built-in) OP-Bus (RS485)/Modbus RTU, CANopen® Assigned switching and protective elements Power Wiring IEC (Typ B, gG) 150 % overload (CT/I _H , at 50 °C) Notor feeder 150 % overload (CT/I _H , at 50 °C) 150 % overload (CT/I _H , at 50 °C) DX-LM3-040 DX-LM3-050 DX-LM3-048 DX-SIN3-048 DX-SR022-5K1	Analog outputs			2, parameterizable, 0 - 10 V, 0/4 - 20 mA
Relay outputs 2, parameterizable, 1 N/O and 1 changeover contact, 6 A (250 V, AC-1) / 5 A (30 V, DC-1) Interface/field bus (built-in) Assigned switching and protective elements Power Wiring IEC (Typ B, gG) 150 % overload (CT/l _H , at 50 °C) Motor feeder 150 % overload (CT/l _H , at 50 °C) 150 % overload (CT/l _H , at 50 °C) DX-LM3-050 DX-LM3-050 DX-SIN3-048 10 % duty factor (DF) DX-BR022-5K1	Digital inputs			3, parameterizable, max. 30 VDC, max. 5 for non-parameterized analog inputs
Interface/field bus (built-in) Assigned switching and protective elements Power Wiring IEC (Typ B, gG) 150 % overload (CT/I _H , at 50 °C) 150 % overload (CT/I _H , at 50 °C) 150 % overload (CT/I _H , at 50 °C) 150 % overload (CT/I _H , at 50 °C) 150 % overload (CT/I _H , at 50 °C) 150 % overload (CT/I _H , at 50 °C) DX-LM3-050 DX-LM3-050 DX-SIN3-048 DX-BR022-5K1	Digital outputs			2, parameterizable, 24 V DC
Assigned switching and protective elements Power Wiring FAZ-B50/3 150 % overload (CT/I _H , at 50 °C) DX-LN3-040 Motor feeder DX-LN3-050 150 % overload (CT/I _H , at 50 °C) DX-LM3-050 150 % overload (CT/I _H , at 50 °C) DX-SIN3-048 10 % duty factor (DF) DX-BR022-5K1	Relay outputs			
Power Wiring FAZ-B50/3 150 % overload (CT/l _H , at 50 °C) DX-LN3-040 Motor feeder DX-LN3-050 150 % overload (CT/l _H , at 50 °C) DX-LM3-050 150 % overload (CT/l _H , at 50 °C) DX-SIN3-048 10 % duty factor (DF) DX-BR022-5K1	Interface/field bus (built-in)			OP-Bus (RS485)/Modbus RTU, CANopen®
IEC (Typ B, gG) FAZ-B50/3 150 % overload (CT/I _H , at 50 °C) DX-LN3-040 Motor feeder DX-LN3-040 150 % overload (CT/I _H , at 50 °C) DX-LM3-050 150 % overload (CT/I _H , at 50 °C) DX-SIN3-048 10 % duty factor (DF) DX-BR022-5K1	Assigned switching and protective elements			
150 % overload (CT/I _H , at 50 °C) DX-LN3-040 Motor feeder DX-LN3-050 150 % overload (CT/I _H , at 50 °C) DX-LM3-050 150 % overload (CT/I _H , at 50 °C) DX-SIN3-048 10 % duty factor (DF) DX-BR022-5K1	Power Wiring			
Motor feeder Motor feeder 150 % overload (CT/l _H , at 50 °C) DX-LM3-050 150 % overload (CT/l _H , at 50 °C) DX-SIN3-048 10 % duty factor (DF) DX-BR022-5K1	IEC (Typ B, gG)			FAZ-B50/3
150 % overload (CT/I _H , at 50 °C) DX-LM3-050 150 % overload (CT/I _H , at 50 °C) DX-SIN3-048 10 % duty factor (DF) DX-BR022-5K1	150 % overload (CT/I _H , at 50 °C)			DX-LN3-040
150 % overload (CT/I _H , at 50 °C) DX-SIN3-048 10 % duty factor (DF) DX-BR022-5K1	Motor feeder			
10 % duty factor (DF) DX-BR022-5K1	150 % overload (CT/I _H , at 50 °C)			DX-LM3-050
	150 % overload (CT/I _H , at 50 °C)			DX-SIN3-048
20 % duty factor (DF) DX-BR022-9K2	10 % duty factor (DF)			DX-BR022-5K1
	20 % duty factor (DF)			DX-BR022-9K2

Design verification as per IEC/EN 61439

echnical data for design verification			
Rated operational current for specified heat dissipation	In	Α	39
Equipment heat dissipation, current-dependent	P_{vid}	W	444
EC/EN 61439 design verification			
10.2 Strength of materials and parts			
10.2.2 Corrosion resistance			Meets the product standard's requirements.
10.2.3.1 Verification of thermal stability of enclosures			Meets the product standard's requirements.
10.2.3.2 Verification of resistance of insulating materials to normal heat			Meets the product standard's requirements.
10.2.3.3 Verification of resistance of insulating materials to abnormal heat and fire due to internal electric effects $$			Meets the product standard's requirements.
10.2.4 Resistance to ultra-violet (UV) radiation			Meets the product standard's requirements.
10.2.5 Lifting			Does not apply, since the entire switchgear needs to be evaluated.
10.2.6 Mechanical impact			Does not apply, since the entire switchgear needs to be evaluated.
10.2.7 Inscriptions			Meets the product standard's requirements.
10.3 Degree of protection of ASSEMBLIES			Does not apply, since the entire switchgear needs to be evaluated.
10.4 Clearances and creepage distances			Meets the product standard's requirements.
10.5 Protection against electric shock			Does not apply, since the entire switchgear needs to be evaluated.
10.6 Incorporation of switching devices and components			Does not apply, since the entire switchgear needs to be evaluated.
10.7 Internal electrical circuits and connections			Is the panel builder's responsibility.
10.8 Connections for external conductors			Is the panel builder's responsibility.
10.9 Insulation properties			
10.9.2 Power-frequency electric strength			Is the panel builder's responsibility.
10.9.3 Impulse withstand voltage			Is the panel builder's responsibility.
10.9.4 Testing of enclosures made of insulating material			Is the panel builder's responsibility.
10.10 Temperature rise			The panel builder is responsible for the temperature rise calculation. Eaton will provide heat dissipation data for the devices.

10.11 Short-circuit rating	Is the panel builder's responsibility. The specifications for the switchgear must be observed.
10.12 Electromagnetic compatibility	Is the panel builder's responsibility. The specifications for the switchgear must be observed.
10.13 Mechanical function	The device meets the requirements, provided the information in the instruction leaflet (IL) is observed.

Technical data ETIM 5.0

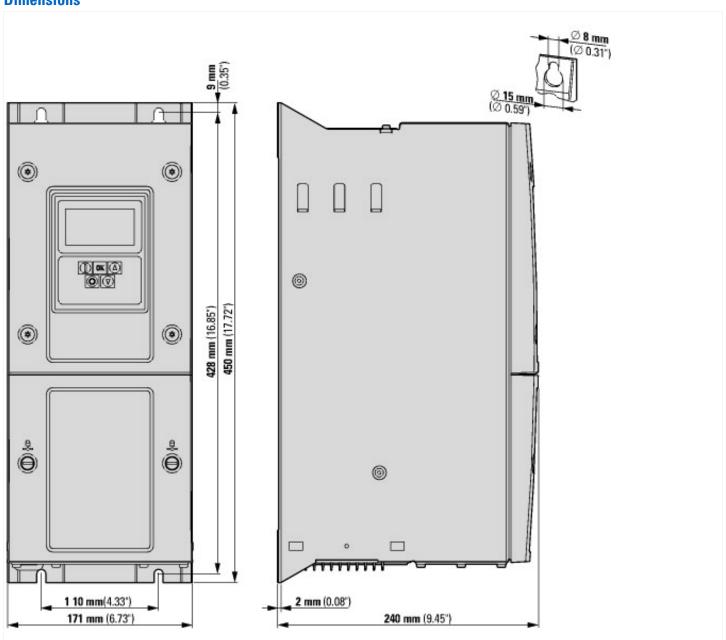
echnical data ETIM 5.0		
ow-voltage industrial components (EG000017) / Frequency controller =< 1 kV (I		
ectric engineering, automation, process control engineering / Electrical drive	/ Static frequency conver	ter / Static frequency converter = < 1 kv (ecl@ss8-27-02-31-01 [AKE177010])
lains voltage	V	380 - 480
lains frequency		50/60 Hz
umber of phases input		3
umber of phases output		3
lax. output frequency	Hz	500
ated output voltage	V	400
leasuring output current	А	39
utput power at rated output voltage	kW	18.5
lax. output at quadratic load at rated output voltage	kW	18.5
lax. output at linear load at rated output voltage	kW	18.5
lith control unit		Yes
pplication in industrial area permitted		Yes
pplication in domestic- and commercial area permitted		Yes
upporting protocol for TCP/IP		No
upporting protocol for PROFIBUS		Yes
upporting protocol for CAN		Yes
upporting protocol for INTERBUS		No
upporting protocol for ASI		No
upporting protocol for KNX		No
upporting protocol for MODBUS		Yes
upporting protocol for Data-Highway		No
upporting protocol for DeviceNet		No
upporting protocol for SUCONET		No
upporting protocol for LON		No
upporting protocol for PROFINET IO		Yes
upporting protocol for PROFINET CBA		No
upporting protocol for SERCOS		No
upporting protocol for Foundation Fieldbus		No
upporting protocol for EtherNet/IP		Yes
upporting protocol for AS-Interface Safety at Work		No
upporting protocol for DeviceNet Safety		No
upporting protocol for INTERBUS-Safety		No
upporting protocol for PROFIsafe		No
upporting protocol for SafetyBUS p		No
upporting protocol for other bus systems		No
umber of HW-interfaces industrial Ethernet		0
umber of HW-interfaces PROFINET		0
umber of HW-interfaces RS-232		0
umber of HW-interfaces RS-422		0
umber of HW-interfaces RS-485		1
umber of HW-interfaces serial TTY		0
umber of HW-interfaces USB		1
umber of HW-interfaces 03B		0
umber of HW-interfaces parallel umber of HW-interfaces other		
		0 No.
/ith optical interface /ith PC connection		No Yes

Integrated braking resistance		Yes
4-quadrant operation possible		No
Type of converter		U converter
Degree of protection (IP)		IP55
Height	mm	450
Width	mm	171
Depth	mm	240
Relative symmetric net frequency tolerance	%	5
Relative symmetric net current tolerance	%	10

Approvals

Product Standards	UL 508C; CSA-C22.2 No. 14; IEC/EN61800-3; IEC/EN61800-5; CE marking
UL File No.	E172143
UL Category Control No.	NMMS, NMMS7
CSA File No.	UL report applies to both US and Canada
North America Certification	UL listed, certified by UL for use in Canada
Specially designed for North America	No
Suitable for	Branch circuits
Max. Voltage Rating	3~ 480 V AC IEC: TN-S UL/CSA: "Y" (Solidly Grounded Wey)
Degree of Protection	IEC: IP55

Dimensions



Additional product information (links) IL04020011Z DA1 variable frequency drives (FS4 - 7) IL04020011Z DA1 variable frequency drives (FS4 - 7) IL04020011Z DA1 variable frequency drives (FS4 - 7) MN04020005Z DA1 variable frequency drive, manual MN04020005Z Frequenzumrichter DA1, Handbuch - Deutsch MN04020005Z DA1 variable frequency drive, manual - English CA04020001Z_EN-INT Product range catalog: Efficient Engineering for starting and controlling motors.