

Variable Frequency Drive, 3~/3~ 400 V, 18 A, 7.5 kW, Vector control, EMC-Filter, Brake-Chopper



Part no. DA1-34018FB-A6SC Article no. 169062 Catalog No. DA1-34018FB-A6SC

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Delivery programme			
Product range			Variable frequency drives
Rated operational voltage	U _e		400 V AC, 3-phase
Output voltage with V_{e}	U ₂		400 V AC, 3-phase
Mains voltage (50/60Hz)	U_{LN}	V	380 (-10%) - 480 (+10%)
Rated operational current			
At 150% overload	I _e	Α	18
Note			Rated operational current at an operating frequency of 4 kHz and an ambient air temperature of +40 $^{\circ}\text{C}$
Note			Overload cycle for 60 s every 600 s
Assigned motor rating			
Note			for normal internally and externally ventilated 4 pole, three-phase asynchronous motors with 1500 rpm ⁻¹ at 50 Hz or 1800 min ⁻¹ at 60 Hz
Note			Overload cycle for 60 s every 600 s
Note			at 400 V, 50 Hz
150 % Overload	P	kW	7.5
150 % Overload	I _e	Α	15.2
Note			at 440 - 480 V, 60 Hz
150 % Overload	P	HP	10
150 % Overload	I _e	Α	14
Degree of Protection			IP66/NEMA 4X
Interface/field bus (built-in)			OP-Bus (RS485)/Modbus RTU, CANopen®
Fieldbus connection (optional)			Ethernet IP DeviceNet PROFIBUS PROFINET Modbus-TCP EtherCAT BACnet/IP SmartWire-DT
Fitted with			Radio interference suppression filter Brake chopper Additional PCB protection 7-digital display assembly Local controls
Frame size			FS3
Connection to SmartWire-DT			with SmartWire-DT module DX-NET-SWD2

Technical data General

Uclicial			
Standards			Specification for general requirements: IEC/EN 61800-2 EMC requirements: IEC/EN 61800-3 Safety requirements: IEC/EN 61800-5-1
Certifications			CE, cUL, UL, c-Tick, Ukr Sepro, EAC
Production quality			RoHS, ISO 9001
Climatic proofing	ρ_{W}	%	< 95%, average relative humidity (RH), non-condensing, non-corrosive (EN 50178)
Ambient temperature		°C	
operation (150 % overload)	8	°C	-10 - +40
Storage	9	°C	-40 - +60
Radio interference level			
Radio interference class (EMC)			C1, C2, C3, depending on the motor cable length, the connected load, and ambient conditions. External radio interference suppression filters (optional) may be necessary.
Environment (EMC)			1st and 2nd environments

maximum motor cable length	l	m	C1 ≤ 1 m C2 ≤ 5 m C3 ≤ 25 m
Mounting position			Vertical
Altitude		m	0 - 1000 m above sea level above 1000 m with 1 % performance reduction per 100 m max. 4000 m
Degree of Protection			IP66/NEMA 4X
Protection against direct contact			BGV A3 (VBG4, finger- and back-of-hand proof)
Main circuit			
Supply			
Rated operational voltage	U _e		400 V AC, 3-phase
Mains voltage (50/60Hz)	U_{LN}	V	380 (-10%) - 480 (+10%)
Input current (150% overload)	I _{LN}	Α	18.1
System configuration			AC supply systems with earthed center point
Supply frequency	f_{LN}	Hz	50/60
Frequency range	f _{LN}	Hz	48 - 62
Mains switch-on frequency			Maximum of one time every 30 seconds
Power section			
Function			Frequency inverter with internal DC link and IGBT inverter
Overload current (150% overload)	IL	Α	27
max. starting current (High Overload)	I _H	%	200
Note about max. starting current			for 4 seconds
Output voltage with V _e	U_2		400 V AC, 3-phase
Output Frequency	f ₂	Hz	0 - 50/60 (max. 500)
Switching frequency	f _{PWM}	kHz	8
Ownering in equation	PVVIVI	KIIZ	adjustable 4 - 24 (audible)
Operation Mode			U/f control Speed control with slip compensation sensorless vector control (SLV) optional: Vector control with feedback (CLV)
Frequency resolution (setpoint value)	Δf	Hz	0.1
Rated operational current			
At 150% overload	I _e	Α	18
Note			Rated operational current at an operating frequency of 4 kHz and an ambient air temperature of +40 $^{\circ}\text{C}$
Power loss			
Heat dissipation at rated operational current	P_V	W	300
Efficiency	η	%	97
Maximum leakage current to ground (PE) without motor	I _{PE}	mA	1.55
Fitted with			Radio interference suppression filter Brake chopper Additional PCB protection 7-digital display assembly Local controls
Safety function			STO (Safe Torque Off)
Frame size			FS3
Motor feeder			
Note			for normal internally and externally ventilated 4 pole, three-phase asynchronous motors with 1500 rpm ⁻¹ at 50 Hz or 1800 min ⁻¹ at 60 Hz
Note			Overload cycle for 60 s every 600 s
Note			at 400 V, 50 Hz
150 % Overload	P	kW	7.5
Note			at 440 - 480 V, 60 Hz
150 % Overload	P	HP	10
maximum permissible cable length	I	m	screened: 100 screened, with motor choke: 200 unscreened: 150 unscreened, with motor choke: 300
Apparent power			
Apparent power at rated operation 400 V	S	kVA	12.47

External control voltage Uc V 24 V DC (max. 10 mA) Reference voltage Us V 10 V DC (max. 10 mA) Analog inputs Analog outputs Analog outputs Analog outputs Relay out				
Standard braking torque DC braking torque Braking torque with external braking resistance minimum external braking resistance minimum external braking resistance Minimum external braking resistance Minimum external braking resistance Muc V 24 V DC (max. 100 mA) Stateral control voltage Uc V 24 V DC (max. 100 mA) Stateral control voltage Ug V 24 V DC (max. 100	Apparent power at rated operation 480 V	S	kVA	14.96
DC braking torque Braking torque with external braking resistance minimum external braking resistance minimum external braking resistance minimum external braking resistance Switch-on threshold for the braking transistor Upc V 780 V DC Switch-on threshold for the braking transistor Upc V 940 V DC (max. 100 mA) Seteranal control voltage Upc V 100 V DC (max. 100 mA) Seteranal control voltage Upc V 24 V DC (max. 100 mA) Seteranal control voltage Upc V 24 V DC (max. 100 mA) Seteranal control voltage Upc V 24 V DC (max. 100 mA) Seteranal control voltage Upc V 24 V DC (max. 100 mA) Seteranal control voltage Upc V 24 V DC (max. 100 mA) Seteranal control voltage Upc V 24 V DC (max. 100 mA) Seteranal control voltage Upc V 24 V DC (max. 100 mA) Upc Upc V 25 V 2	Braking function			
Braking torque with external braking resistance minimum external braking resistance minimum external braking resistance Rmin	Standard braking torque			max. 30 % M_N
minimum external braking resistance Switch-on threshold for the braking transistor Upc V 780 V DC Switch-on threshold for the braking transistor Upc V 780 V DC Switch-on threshold for the braking transistor Upc V 24 V DC (max. 100 mA) 10 V DC (max. 10 mA)	DC braking torque			100 %, adjustable
Switch-on threshold for the braking transistor UDC V 780 V DC Control section External control voltage Uc V 24 V DC (max. 100 mA) Reference voltage Un V 10 V DC (max. 100 mA) Analog inputs Analog outputs Analog outputs Digital outputs Relay outputs	Braking torque with external braking resistance			max. 100% rated operational current I_{e} , with external braking resistance
Solution Section External control voltage U _C V 24 V DC (max. 100 mA) Seference voltage U _S V 10 V DC (max. 10 mA) Analog inputs Analog outputs Analog	minimum external braking resistance	R _{min}	Ω	50
External control voltage Uc V 24 V DC (max. 10 mA) Reference voltage Us V 10 V DC (max. 10 mA) Analog inputs Analog outputs Analog outputs Analog outputs Relay out	Switch-on threshold for the braking transistor	U _{DC}	V	780 V DC
Reference voltage Us V 10 V DC (max. 10 mA) 10 V DC, 0/4 - 20 mA 2, parameterizable, 0 - 10 V DC, 0/4 - 20 mA 2, parameterizable, 0 - 10 V DC, 0/4 - 20 mA 3, parameterizable, 0 - 10 V, 0/4 - 20 mA 3, parameterizable, 0 - 10 V, 0/4 - 20 mA 3, parameterizable, max. 30 VDC, max. 5 for non-parameterized analog inputs 2, parameterizable, 24 V DC 3, parameterizable, 1 N/O and 1 changeover contact, 6 A (250 V, AC-1) / 5 A (30 V, DC-1) 10 V DC (max. 10 mA) 2, parameterizable, 0 - 10 V DC, 0/4 - 20 mA 3, parameterizable, max. 30 VDC, max. 5 for non-parameterized analog inputs 2, parameterizable, 24 V DC 2, parameterizable, 1 N/O and 1 changeover contact, 6 A (250 V, AC-1) / 5 A (30 V, DC-1) 10 V DC (max. 10 mA) 3, parameterizable, max. 30 VDC, max. 5 for non-parameterized analog inputs 2, parameterizable, 1 N/O and 1 changeover contact, 6 A (250 V, AC-1) / 5 A (30 V, DC-1) 4, parameterizable, 1 N/O and 1 changeover contact, 6 A (250 V, AC-1) / 5 A (30 V, DC-1) 4, parameterizable, 1 N/O and 1 changeover contact, 6 A (250 V, AC-1) / 5 A (30 V, DC-1) 4, parameterizable, 1 N/O and 1 changeover contact, 6 A (250 V, AC-1) / 5 A (30 V, DC-1) 4, parameterizable, 1 N/O and 1 changeover contact, 6 A (250 V, AC-1) / 5 A (30 V, DC-1) 4, parameterizable, 1 N/O and 1 changeover contact, 6 A (250 V, AC-1) / 5 A (30 V, DC-1) 5, parameterizable, 1 N/O and 1 changeover contact, 6 A (250 V, AC-1) / 5 A (30 V, DC-1) 6, parameterizable, 1 N/O and 1 changeover contact, 6 A (250 V, AC-1) / 5 A (30 V, DC-1) 6, parameterizable, 1 N/O and 1 changeover contact, 6 A (250 V, AC-1) / 5 A (30 V, DC-1) 7, parameterizable, 1 N/O and 1 changeover contact, 6 A (250 V, AC-1) / 5 A (30 V, DC-1) 7, parameterizable, 1 N/O and 1 changeover contact, 6 A (250 V, AC-1) / 5 A (30 V, DC-1) 7, parameterizable, 1 N/O and 1 changeover contact, 6 A (250 V, AC-1) / 5 A (30 V, DC-1) 7, parameterizable, 1 N/O and 1 changeover contact, 6 A (250 V, AC-1) / 5 A (30 V, DC-1) 7, parameterizable, 1 N/O and 1 changeover contact, 6 A (250 V, AC-1) /	Control section			
Analog inputs Analog inputs Analog outputs Analog o	External control voltage	U _c	V	24 V DC (max. 100 mA)
Analog outputs Analog	Reference voltage	U _s	V	10 V DC (max. 10 mA)
Digital inputs 3, parameterizable, max. 30 VDC, max. 5 for non-parameterized analog inputs 2, parameterizable, 24 V DC 2, parameterizable, 1 N/O and 1 changeover contact, 6 A (250 V, AC-1) / 5 A (30 V, DC-1) Assigned switching and protective elements Power Wirring IEC (Typ B, gG) UL (Class CC or J) A 25 150 % overload (CT/I _H , at 50 °C) Motor feeder 150 % overload (CT/I _H , at 50 °C) DX-LM3-035 DX-LM3-035 DX-SIN3-023	Analog inputs			2, parameterizable, 0 - 10 V DC, 0/4 - 20 mA
Digital outputs 2, parameterizable, 24 V DC 2, parameterizable, 1 N/O and 1 changeover contact, 6 A (250 V, AC-1) / 5 A (30 V, DC-1) nterface/field bus (built-in) Assigned switching and protective elements Power Wirring IEC (Typ B, gG) UL (Class CC or J) A 25 150 % overload (CT/I _H , at 50 °C) Motor feeder 150 % overload (CT/I _H , at 50 °C) DX-LM3-035 DX-SIN3-023	Analog outputs			2, parameterizable, 0 - 10 V, 0/4 - 20 mA
Relay outputs 2, parameterizable, 1 N/O and 1 changeover contact, 6 A (250 V, AC-1) / 5 A (30 V, DC-1) OP-Bus (RS485)/Modbus RTU, CANopen® Assigned switching and protective elements Power Wiring IEC (Typ B, gG) IEC (Typ B, gG) A 25 150 % overload (CT/I _H , at 50 °C) DX-LN3-025 DX-LN3-025 DX-LM3-035 DX-SIN3-023	Digital inputs			3, parameterizable, max. 30 VDC, max. 5 for non-parameterized analog inputs
DC-1) OP-Bus (RS485)/Modbus RTU, CANopen® Assigned switching and protective elements Power Wiring IEC (Typ B, gG) UL (Class CC or J) A 25 150 % overload (CT/l _H , at 50 °C) Motor feeder 150 % overload (CT/l _H , at 50 °C) DX-LM3-035 DX-SIN3-023	Digital outputs			2, parameterizable, 24 V DC
Sassigned switching and protective elements Sassigned switching and protective elements	Relay outputs			
Power Wiring IEC (Typ B, gG) UL (Class CC or J) A 25 150 % overload (CT/I _H , at 50 °C) Motor feeder 150 % overload (CT/I _H , at 50 °C) DX-LM3-035 DX-SIN3-023	Interface/field bus (built-in)			OP-Bus (RS485)/Modbus RTU, CANopen®
IEC (Typ B, gG)	Assigned switching and protective elements			
UL (Class CC or J) A 25 150 % overload (CT/I _H , at 50 °C) DX-LN3-025 Motor feeder DX-LN3-025 150 % overload (CT/I _H , at 50 °C) DX-LM3-035 150 % overload (CT/I _H , at 50 °C) DX-SIN3-023	Power Wiring			
150 % overload (CT/I _H , at 50 °C) Motor feeder 150 % overload (CT/I _H , at 50 °C) DX-LM3-025 DX-LM3-025 DX-LM3-025 DX-LM3-035 DX-SIN3-023	IEC (Typ B, gG)			FAZ-B25/3
Motor feeder DX-LM3-035 150 % overload (CT/I _H , at 50 °C) DX-SIN3-023	UL (Class CC or J)		Α	25
150 % overload (CT/I _H , at 50 °C) DX-LM3-035 150 % overload (CT/I _H , at 50 °C) DX-SIN3-023	150 % overload (CT/I _H , at 50 °C)			DX-LN3-025
150 % overload (CT/I _H , at 50 °C) DX-SIN3-023	Motor feeder			
** *** *** *** *** *** *** *** *** ***	150 % overload (CT/I _H , at 50 °C)			DX-LM3-035
0 % duty factor (DF) DX-BR050-3K1	150 % overload (CT/I _H , at 50 °C)			DX-SIN3-023
	10 % duty factor (DF)			DX-BR050-3K1

DX-BR050-5K1

Design verification as per IEC/EN 61439

20 % duty factor (DF)

Jesign verification as per IEC/EN 61439 Technical data for design verification			
· ·			
Rated operational current for specified heat dissipation	In	Α	18
Equipment heat dissipation, current-dependent	P _{vid}	W	300
EC/EN 61439 design verification			
10.2 Strength of materials and parts			
10.2.2 Corrosion resistance			Meets the product standard's requirements.
10.2.3.1 Verification of thermal stability of enclosures			Meets the product standard's requirements.
10.2.3.2 Verification of resistance of insulating materials to normal heat			Meets the product standard's requirements.
10.2.3.3 Verification of resistance of insulating materials to abnormal heat and fire due to internal electric effects $$			Meets the product standard's requirements.
10.2.4 Resistance to ultra-violet (UV) radiation			Meets the product standard's requirements.
10.2.5 Lifting			Does not apply, since the entire switchgear needs to be evaluated.
10.2.6 Mechanical impact			Does not apply, since the entire switchgear needs to be evaluated.
10.2.7 Inscriptions			Meets the product standard's requirements.
10.3 Degree of protection of ASSEMBLIES			Does not apply, since the entire switchgear needs to be evaluated.
10.4 Clearances and creepage distances			Meets the product standard's requirements.
10.5 Protection against electric shock			Does not apply, since the entire switchgear needs to be evaluated.
10.6 Incorporation of switching devices and components			Does not apply, since the entire switchgear needs to be evaluated.
10.7 Internal electrical circuits and connections			Is the panel builder's responsibility.
10.8 Connections for external conductors			Is the panel builder's responsibility.
10.9 Insulation properties			
10.9.2 Power-frequency electric strength			Is the panel builder's responsibility.
10.9.3 Impulse withstand voltage			Is the panel builder's responsibility.
10.9.4 Testing of enclosures made of insulating material			Is the panel builder's responsibility.
10.10 Temperature rise			The panel builder is responsible for the temperature rise calculation. Eaton will provide heat dissipation data for the devices.

10.11 Short-circuit rating	Is the panel builder's responsibility. The specifications for the switchgear must be observed.
10.12 Electromagnetic compatibility	Is the panel builder's responsibility. The specifications for the switchgear must be observed.
10.13 Mechanical function	The device meets the requirements, provided the information in the instruction leaflet (IL) is observed.

Technical data ETIM 5.0

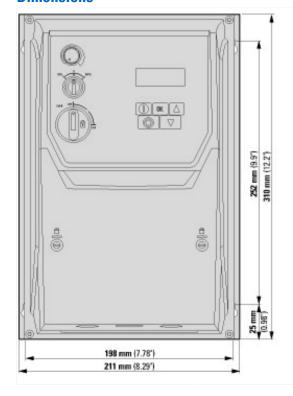
echnical data ETIM 5.0		
ow-voltage industrial components (EG000017) / Frequency controller =< 1 kV (I		
ectric engineering, automation, process control engineering / Electrical drive	/ Static frequency conver	ter / Static frequency converter = < 1 kv (ecl@ss8-27-02-31-01 [AKE177010])
lains voltage	V	380 - 480
lains frequency		50/60 Hz
umber of phases input		3
umber of phases output		3
ax. output frequency	Hz	500
ated output voltage	V	400
easuring output current	А	18
utput power at rated output voltage	kW	7.5
ax. output at quadratic load at rated output voltage	kW	7.5
ax. output at linear load at rated output voltage	kW	7.5
/ith control unit		Yes
pplication in industrial area permitted		Yes
pplication in domestic- and commercial area permitted		Yes
upporting protocol for TCP/IP		No
upporting protocol for PROFIBUS		Yes
upporting protocol for CAN		Yes
upporting protocol for INTERBUS		No
upporting protocol for ASI		No
upporting protocol for KNX		No
upporting protocol for MODBUS		Yes
upporting protocol for Data-Highway		No
upporting protocol for DeviceNet		No
upporting protocol for SUCONET		No
upporting protocol for LON		No
upporting protocol for PROFINET IO		Yes
upporting protocol for PROFINET CBA		No
upporting protocol for SERCOS		No
upporting protocol for Foundation Fieldbus		No
upporting protocol for EtherNet/IP		Yes
upporting protocol for AS-Interface Safety at Work		No
upporting protocol for DeviceNet Safety		No
upporting protocol for INTERBUS-Safety		No
upporting protocol for PROFIsafe		No
upporting protocol for SafetyBUS p		No
upporting protocol for other bus systems		No
umber of HW-interfaces industrial Ethernet		0
umber of HW-interfaces PROFINET		0
umber of HW-interfaces RS-232		0
umber of HW-interfaces RS-422		0
umber of HW-interfaces RS-485		1
umber of HW-interfaces serial TTY		0
umber of HW-interfaces USB		1
umber of HW-interfaces parallel		0
umber of HW-interfaces other		0 No.
/ith optical interface /ith PC connection		No Yes

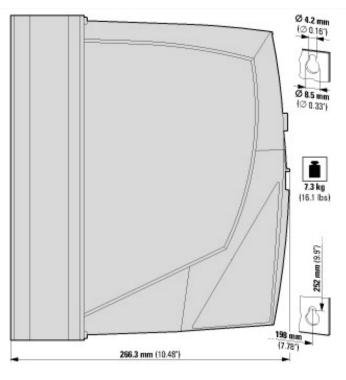
Integrated braking resistance		Yes
4-quadrant operation possible		No
Type of converter		U converter
Degree of protection (IP)		IP66
Height	mm	273
Width	mm	131
Depth	mm	204
Relative symmetric net frequency tolerance	%	5
Relative symmetric net current tolerance	%	10

Approvals

Product Standards	UL 508C; CSA-C22.2 No. 14; IEC/EN61800-3; IEC/EN61800-5; CE marking
UL File No.	E172143
UL Category Control No.	NMMS, NMMS7
CSA File No.	UL report applies to both US and Canada
North America Certification	UL listed, certified by UL for use in Canada
Specially designed for North America	No
Suitable for	Branch circuits
Max. Voltage Rating	3~ 480 V AC IEC: TN-S UL/CSA: "Y" (Solidly Grounded Wey)
Degree of Protection	IEC: IP66

Dimensions





Additional product informat	Additional product information (links)				
IL04020015Z DA1 variable frequency drives (FS2+3, IP66)					
	IL04020015Z DA1 variable frequency drives (FS2+3, IP66)				
MN04020005Z DA1 variable frequency drive, manual					
	MN04020005Z Frequenzumrichter DA1, Handbuch - Deutsch				
	MN04020005Z DA1 variable frequency drive, manual - English				
CA04020001Z_EN-INT Product range catalog: Efficient Engineering for starting and controlling motors.	http://www.eaton.eu/ecm/groups/public/@pub/@europe/@electrical/documents/content/pct_1095238.pdf				