



**Variable Frequency Drive, 3~/3~ 400 V, 202 A, 110 kW, Vector control, EMC-Filter, Brake-Chopper**

**Part no.** DA1-34202FB-A55N  
**Article no.** 169045  
**Catalog No.** DA1-34202FB-A55N

## Delivery programme

Product range			Variable frequency drives
Rated operational voltage	$U_e$		400 V AC, 3-phase
Output voltage with $V_e$	$U_2$		400 V AC, 3-phase
Mains voltage (50/60Hz)	$U_{LN}$	V	380 (-10%) - 480 (+10%)
<b>Rated operational current</b>			
At 150% overload	$I_e$	A	202
Note			Rated operational current at an operating frequency of 4 kHz and an ambient air temperature of +40 °C
Note			Overload cycle for 60 s every 600 s
<b>Assigned motor rating</b>			
Note			for normal internally and externally ventilated 4 pole, three-phase asynchronous motors with 1500 rpm <sup>-1</sup> at 50 Hz or 1800 min <sup>-1</sup> at 60 Hz
Note			Overload cycle for 60 s every 600 s
Note			at 400 V, 50 Hz
150 % Overload	P	kW	110
150 % Overload	$I_e$	A	196
Note			at 440 - 480 V, 60 Hz
150 % Overload	P	HP	150
150 % Overload	$I_e$	A	180
Degree of Protection			IP55/NEMA 12
Interface/field bus (built-in)			OP-Bus (RS485)/Modbus RTU, CANopen®
Fieldbus connection (optional)			Ethernet IP DeviceNet PROFIBUS PROFINET Modbus-TCP EtherCAT BACnet/IP SmartWire-DT
Fitted with			Radio interference suppression filter Brake chopper 7-digit display assembly DC link choke
Frame size			FS7
Connection to SmartWire-DT			with SmartWire-DT module DX-NET-SWD2

## Technical data

<b>General</b>			
Standards			Specification for general requirements: IEC/EN 61800-2 EMC requirements: IEC/EN 61800-3 Safety requirements: IEC/EN 61800-5-1
Certifications			CE, cUL, UL, c-Tick, Ukr Sepro, EAC
Production quality			RoHS, ISO 9001
Climatic proofing	$\rho_w$	%	< 95%, average relative humidity (RH), non-condensing, non-corrosive (EN 50178)

Ambient temperature		°C	
operation (150 % overload)	θ	°C	-10 - +40
Storage	θ	°C	-40 - +60
Radio interference level			
Radio interference class (EMC)			C1, C2, C3, depending on the motor cable length, the connected load, and ambient conditions. External radio interference suppression filters (optional) may be necessary.
Environment (EMC)			1st and 2nd environments
maximum motor cable length	l	m	C1 ≤ 1 m C2 ≤ 5 m C3 ≤ 25 m
Mounting position			Vertical
Altitude		m	0 - 1000 m above sea level above 1000 m with 1 % performance reduction per 100 m max. 4000 m
Degree of Protection			IP55/NEMA 12
Protection against direct contact			BGV A3 (VBG4, finger- and back-of-hand proof)

## Main circuit

Supply			
Rated operational voltage	$U_e$		400 V AC, 3-phase
Mains voltage (50/60Hz)	$U_{LN}$	V	380 (-10%) - 480 (+10%)
Input current (150% overload)	$I_{LN}$	A	205.9
System configuration			AC supply systems with earthed center point
Supply frequency	$f_{LN}$	Hz	50/60
Frequency range	$f_{LN}$	Hz	48 - 62
Mains switch-on frequency			Maximum of one time every 30 seconds
Power section			
Function			Variable frequency drive with internal DC link, DC link choke and IGBT inverter
Overload current (150% overload)	$I_L$	A	303
max. starting current (High Overload)	$I_H$	%	200
Note about max. starting current			for 4 seconds
Output voltage with $V_e$	$U_2$		400 V AC, 3-phase
Output Frequency	$f_2$	Hz	0 - 50/60 (max. 250)
Switching frequency	$f_{PWM}$	kHz	4 adjustable 4 - 16 (audible)
Operation Mode			U/f control Speed control with slip compensation sensorless vector control (SLV) optional: Vector control with feedback (CLV)
Frequency resolution (setpoint value)	$\Delta f$	Hz	0.1
Rated operational current			
At 150% overload	$I_e$	A	202
Note			Rated operational current at an operating frequency of 4 kHz and an ambient air temperature of +40 °C
Power loss			
Heat dissipation at rated operational current	$P_V$	W	2090
Efficiency	$\eta$	%	98.1
Maximum leakage current to ground (PE) without motor	$I_{PE}$	mA	4.75
Fitted with			Radio interference suppression filter Brake chopper 7-digital display assembly DC link choke
Safety function			STO (Safe Torque Off)
Frame size			FS7
Motor feeder			
Note			for normal internally and externally ventilated 4 pole, three-phase asynchronous motors with 1500 rpm <sup>-1</sup> at 50 Hz or 1800 min <sup>-1</sup> at 60 Hz
Note			Overload cycle for 60 s every 600 s
Note			at 400 V, 50 Hz
150 % Overload	P	kW	110
Note			at 440 - 480 V, 60 Hz

150 % Overload	P	HP	150
maximum permissible cable length	I	m	screened: 100 screened, with motor choke: 200 unscreened: 150 unscreened, with motor choke: 300
Apparent power			
Apparent power at rated operation 400 V	S	kVA	139.95
Apparent power at rated operation 480 V	S	kVA	167.94
Braking function			
Standard braking torque			max. 30 % $M_N$
DC braking torque			100 %, adjustable
Braking torque with external braking resistance			max. 100% rated operational current $I_e$ , with external braking resistance
minimum external braking resistance	$R_{min}$	$\Omega$	6
Switch-on threshold for the braking transistor	$U_{DC}$	V	780 V DC

### Control section

External control voltage	$U_c$	V	24 V DC (max. 100 mA)
Reference voltage	$U_s$	V	10 V DC (max. 10 mA)
Analog inputs			2, parameterizable, 0 - 10 V DC, 0/4 - 20 mA
Analog outputs			2, parameterizable, 0 - 10 V, 0/4 - 20 mA
Digital inputs			3, parameterizable, max. 30 VDC, max. 5 for non-parameterized analog inputs
Digital outputs			2, parameterizable, 24 V DC
Relay outputs			2, parameterizable, 1 N/O and 1 changeover contact, 6 A (250 V, AC-1) / 5 A (30 V, DC-1)
Interface/field bus (built-in)			OP-Bus (RS485)/Modbus RTU, CANopen®

### Assigned switching and protective elements

Power Wiring			
IEC (Typ B, gG)			NZMC3-S250
150 % overload (CT/ $I_H$ , at 50 °C)			DX-LN3-250
Motor feeder			
150 % overload (CT/ $I_H$ , at 50 °C)			DX-LM3-220
150 % overload (CT/ $I_H$ , at 50 °C)			DX-SIN3-250
10 % duty factor (DF)			DX-BR006-18K1
20 % duty factor (DF)			DX-BR006-33K3

## Design verification as per IEC/EN 61439

Technical data for design verification			
Rated operational current for specified heat dissipation	$I_n$	A	202
Equipment heat dissipation, current-dependent	$P_{vid}$	W	2090
IEC/EN 61439 design verification			
10.2 Strength of materials and parts			
10.2.2 Corrosion resistance			Meets the product standard's requirements.
10.2.3.1 Verification of thermal stability of enclosures			Meets the product standard's requirements.
10.2.3.2 Verification of resistance of insulating materials to normal heat			Meets the product standard's requirements.
10.2.3.3 Verification of resistance of insulating materials to abnormal heat and fire due to internal electric effects			Meets the product standard's requirements.
10.2.4 Resistance to ultra-violet (UV) radiation			Meets the product standard's requirements.
10.2.5 Lifting			Does not apply, since the entire switchgear needs to be evaluated.
10.2.6 Mechanical impact			Does not apply, since the entire switchgear needs to be evaluated.
10.2.7 Inscriptions			Meets the product standard's requirements.
10.3 Degree of protection of ASSEMBLIES			Does not apply, since the entire switchgear needs to be evaluated.
10.4 Clearances and creepage distances			Meets the product standard's requirements.
10.5 Protection against electric shock			Does not apply, since the entire switchgear needs to be evaluated.
10.6 Incorporation of switching devices and components			Does not apply, since the entire switchgear needs to be evaluated.
10.7 Internal electrical circuits and connections			Is the panel builder's responsibility.
10.8 Connections for external conductors			Is the panel builder's responsibility.
10.9 Insulation properties			
10.9.2 Power-frequency electric strength			Is the panel builder's responsibility.

10.9.3 Impulse withstand voltage		Is the panel builder's responsibility.
10.9.4 Testing of enclosures made of insulating material		Is the panel builder's responsibility.
10.10 Temperature rise		The panel builder is responsible for the temperature rise calculation. Eaton will provide heat dissipation data for the devices.
10.11 Short-circuit rating		Is the panel builder's responsibility. The specifications for the switchgear must be observed.
10.12 Electromagnetic compatibility		Is the panel builder's responsibility. The specifications for the switchgear must be observed.
10.13 Mechanical function		The device meets the requirements, provided the information in the instruction leaflet (IL) is observed.

## Technical data ETIM 5.0

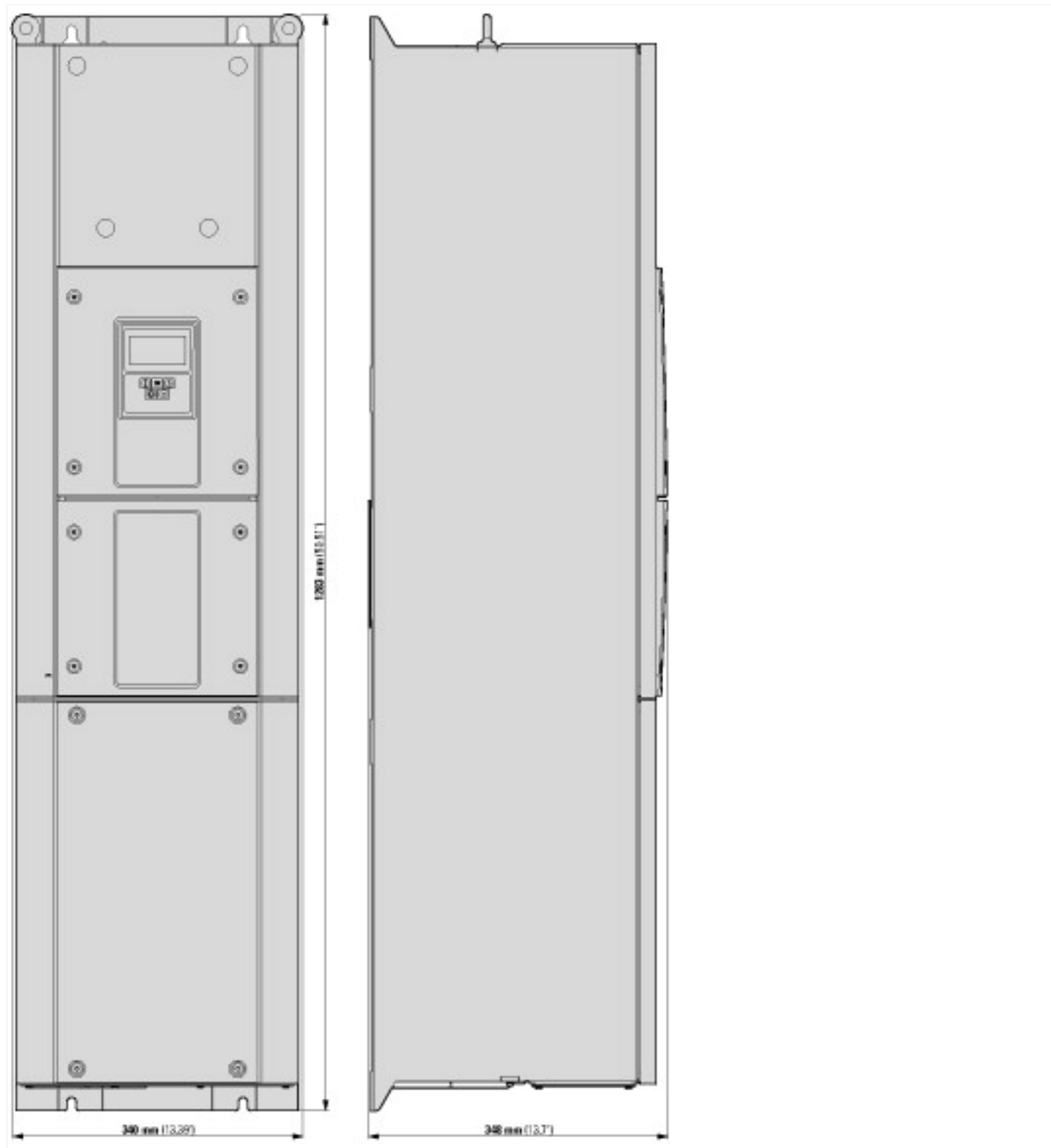
Low-voltage industrial components (EG000017) / Frequency controller =< 1 kV (EC001857)		
Electric engineering, automation, process control engineering / Electrical drive / Static frequency converter / Static frequency converter = < 1 kv (ec1@ss8-27-02-31-01 [AKE177010])		
Mains voltage	V	380 - 480
Mains frequency		50/60 Hz
Number of phases input		3
Number of phases output		3
Max. output frequency	Hz	500
Rated output voltage	V	400
Measuring output current	A	202
Output power at rated output voltage	kW	110
Max. output at quadratic load at rated output voltage	kW	110
Max. output at linear load at rated output voltage	kW	110
With control unit		Yes
Application in industrial area permitted		Yes
Application in domestic- and commercial area permitted		Yes
Supporting protocol for TCP/IP		No
Supporting protocol for PROFIBUS		Yes
Supporting protocol for CAN		Yes
Supporting protocol for INTERBUS		No
Supporting protocol for ASI		No
Supporting protocol for KNX		No
Supporting protocol for MODBUS		Yes
Supporting protocol for Data-Highway		No
Supporting protocol for DeviceNet		No
Supporting protocol for SUCONET		No
Supporting protocol for LON		No
Supporting protocol for PROFINET IO		Yes
Supporting protocol for PROFINET CBA		No
Supporting protocol for SERCOS		No
Supporting protocol for Foundation Fieldbus		No
Supporting protocol for EtherNet/IP		Yes
Supporting protocol for AS-Interface Safety at Work		No
Supporting protocol for DeviceNet Safety		No
Supporting protocol for INTERBUS-Safety		No
Supporting protocol for PROFIsafe		No
Supporting protocol for SafetyBUS p		No
Supporting protocol for other bus systems		No
Number of HW-interfaces industrial Ethernet		0
Number of HW-interfaces PROFINET		0
Number of HW-interfaces RS-232		0
Number of HW-interfaces RS-422		0
Number of HW-interfaces RS-485		1
Number of HW-interfaces serial TTY		0
Number of HW-interfaces USB		1
Number of HW-interfaces parallel		0

Number of HW-interfaces other			0
With optical interface			No
With PC connection			Yes
Integrated braking resistance			Yes
4-quadrant operation possible			No
Type of converter			U converter
Degree of protection (IP)			IP55
Height		mm	1280
Width		mm	330
Depth		mm	360
Relative symmetric net frequency tolerance		%	5
Relative symmetric net current tolerance		%	10

## Approvals

Product Standards			UL 508C; CSA-C22.2 No. 14; IEC/EN61800-3; IEC/EN61800-5; CE marking
UL File No.			E172143
UL Category Control No.			NMMS, NMMS7
CSA File No.			UL report applies to both US and Canada
North America Certification			UL listed, certified by UL for use in Canada
Specially designed for North America			No
Suitable for			Branch circuits
Max. Voltage Rating			3~ 480 V AC IEC: TN-S UL/CSA: "Y" (Solidly Grounded Wey)
Degree of Protection			IEC: IP55

## Dimensions



## Additional product information (links)

### IL04020011Z DA1 variable frequency drives (FS4 - 7)

[IL04020011Z DA1 variable frequency drives \(FS4 - 7\)](#)

[IL04020011Z DA1 variable frequency drives \(FS4 - 7\)](#)

### MN04020005Z DA1 variable frequency drive, manual

[MN04020005Z Frequenzumrichter DA1, Handbuch - Deutsch](#)

[MN04020005Z DA1 variable frequency drive, manual - English](#)

CA04020001Z\_EN-INT Product range catalog:  
Efficient Engineering for starting and  
controlling motors.

[http://www.eaton.eu/ecm/groups/public/@pub/@europe/@electrical/documents/content/pct\\_1095238.pdf](http://www.eaton.eu/ecm/groups/public/@pub/@europe/@electrical/documents/content/pct_1095238.pdf)