

## BDC-RO5A-230

**Up/down control of 1 rollerblind motor**

**Up/down interlocking for motor**

**AC power supply**

**Channel coding by BGP-COD-BAT**

**Design for mounting in euro box**



### OUTPUT SPECIFICATIONS

<b>Outputs</b>			
Resistive loads	AC 1 DC 1 or	1 SPST relay & 1 SPDT relay 5 A/250 VAC (1250 VA) 0.25 A/250 VDC (62 W)	
Inductive loads	AC 15 DC 13	2.5 A/230 VAC 5 A/24 VDC	
Mechanical lifetime		≥ 30 x 106 operations	
			Electrical lifetime (at max load) AC 1 ≥ 2.0 x 105 operations Operating frequency ≤ 7200 operations/h Insulation voltage Outputs - smart-house ≥ 4 kVAC (rms)
			<b>Response time</b> 1 pulse train

### GENERAL SPECIFICATIONS

<b>Output OFF delay</b>		<b>Humidity</b> (non-condensing)	20 to 80%
Upon loss of smart-house carrier	20 ms		
<b>Power ON delay</b>	Typ. 2 s	<b>Mechanical resistance</b>	
<b>Power OFF delay</b>	≤ 1 s	Shock	15 G (11 ms)
<b>Environment</b>		Vibration	2 G (6 to 55 Hz)
Pollution degree	3 (IEC 60664)	<b>Dimensions</b> (h x w x d)	50 x 50 x 30
Operating temperature	-20° to +50°C (-4° to +122°F)	<b>Material</b>	ABS
Storage temperature	-50° to +85°C (-58° to +185°F)	<b>Weight</b>	100 g

### SUPPLY SPECIFICATIONS

<b>Power supply AC types</b>	Installations cat. III (IEC 60664)	<b>Insulation voltage</b>	
Rated operational voltage through wire L & N	230 VAC ± 15% (IEC 60038)	Supply - smart-house	≥ 4 kVAC (rms)
Frequency	45 to 65 Hz	Supply - Outputs	≥ 4 kVAC (rms)
Drop-out tolerance	≤ 40 ms	smart-house - Outputs	≥ 4 kVAC (rms)
Power consumption	Typ. 3.3 VA		
Power dissipation	≤ 2 W		
Transient protection volt.	4 kV		
		<b>Consumption on smart-house</b>	
		Normal consumption	≤ 0.5 mA
		Consumption 1 relay on	≤ 1.8 mA
		Consumption 2 relay on	≤ 3.2 mA

### MODE OF OPERATION

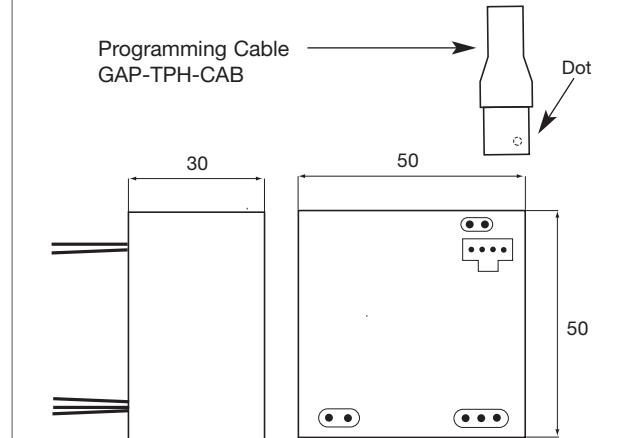
As indicated on the wiring diagram, there are two relays in series to control the motor. O1 is used to switch the Motor ON/OFF and O2 is used to control the direction of the Motor UP/DOWN. In this way, it is made sure that the motors are not controlled UP and DOWN at the same time (interlocking). O1 and O2 may be coded individually by means of the code programmer BGP-COD-BAT. The default setting of the module is to switch all outputs off in case of loss of smart-house carrier signal. The smart-house controller provides intelligent functions that makes it easy for the user to control the rollerblind motors individually or several at the same time (all UP or all DOWN).

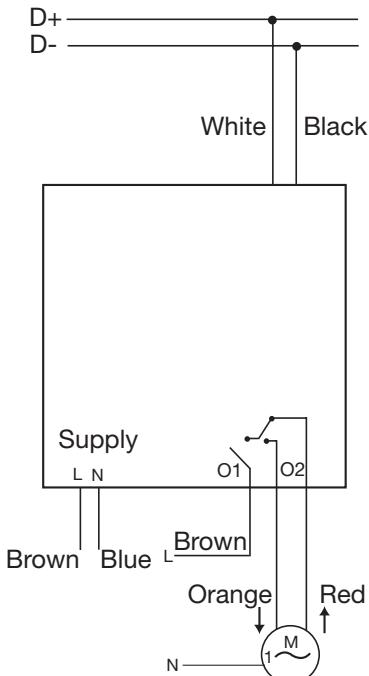
### TYPE SELECTION

**Supply**  
230 VAC

**Ordering no.**  
BDC-RO5A-230

### DIMENSIONS (mm)



**WIRING DIAGRAM****Wiring Connections**

Bus:	White =	smart-house signal, D+
	Black =	smart-house signal, D-
Supply:	Brown =	L
	Blue =	N
Output:	Brown =	O1, Motor on/off
	Orange =	O2, Motor up/down
	Red =	O2, Motor up/down

Bus wires: 2 x 0,75 mm<sup>2</sup>  
 Supply, Output: 250V isolation, single core, 150 mm  
 5 x 1,5 mm<sup>2</sup>  
 250V isolation, single core, 150 mm

**ACCESSORIES**

Programming cable to BGP-COD-BAT

GAP-TPH-CAB